

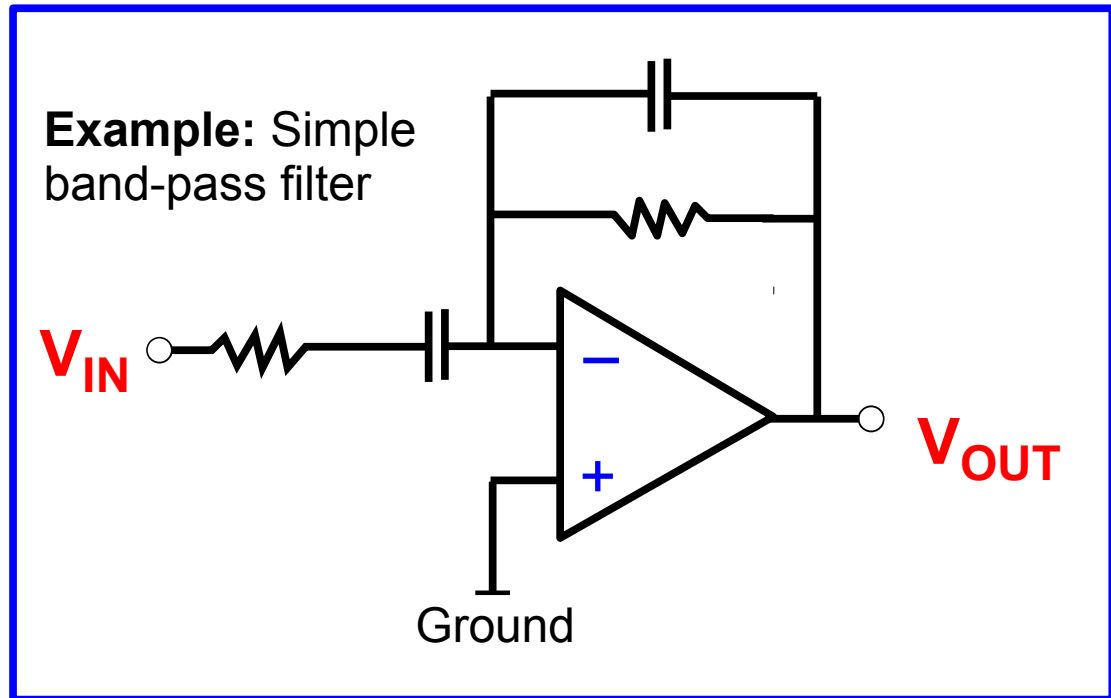
# Lab 9: Active Filter Circuits

# Active Filters

Frequency-dependent transfer function  $G(\omega) = V_{OUT}/V_{IN}$

Active: Supply current to transistors, op-amps

Passive: Only resistors, capacitors, inductors, diodes, etc (earlier labs)



## Advantages of active filtering over passive filtering

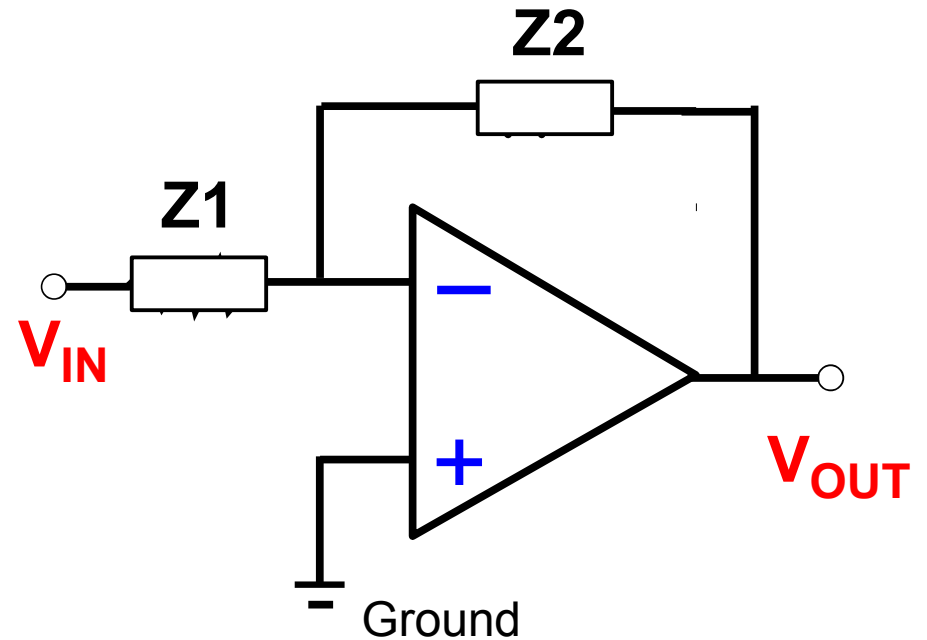
- \* Compensate for filter loss with amplification
- \* Performance nearly immune from influence of input/output circuits
- \* Don't need bulky, expensive inductors

## Disadvantages

- \* Consumes power
- \* Can introduce electrical noise

# Review of ideal Op-Amp

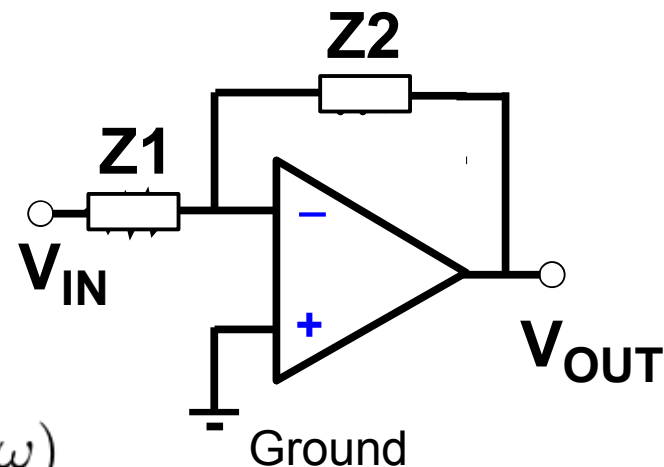
Very high input impedance  
Negligible current flows into device  
Inverting input (–)  
Non-inverting input (+)  
Extremely high amplification  
Clever use of feedback



Inverting amplifier

$$\frac{V_{OUT}}{V_{IN}} = -\frac{Z2}{Z1}$$

## Poles and Zeroes



$$\frac{V_{OUT}(\omega)}{V_{IN}(\omega)} = -\frac{Z_2(\omega)}{Z_1(\omega)} = G(\omega) = \frac{N(\omega)}{D(\omega)}$$

Numerator:  $N(\omega) = (\omega_{N1} + j\omega)(\omega_{N2} + j\omega) \times \dots (\omega_{Nm} + j\omega)$

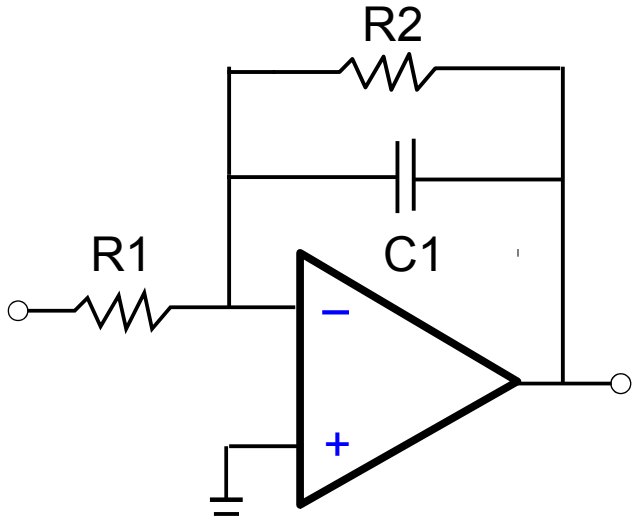
Denominator:  $D(\omega) = (\omega_{D1} + j\omega)(\omega_{D2} + j\omega) \times \dots (\omega_{Dm'} + j\omega)$

$$m \leq m'$$

**Zeroes:** Frequencies ( $\omega_N$ ) that make the numerator zero

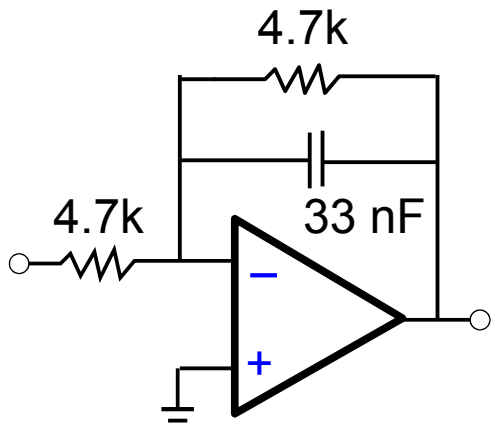
**Poles:** Frequencies ( $\omega_D$ ) that make the denominator zero

# Example: Low-pass filter



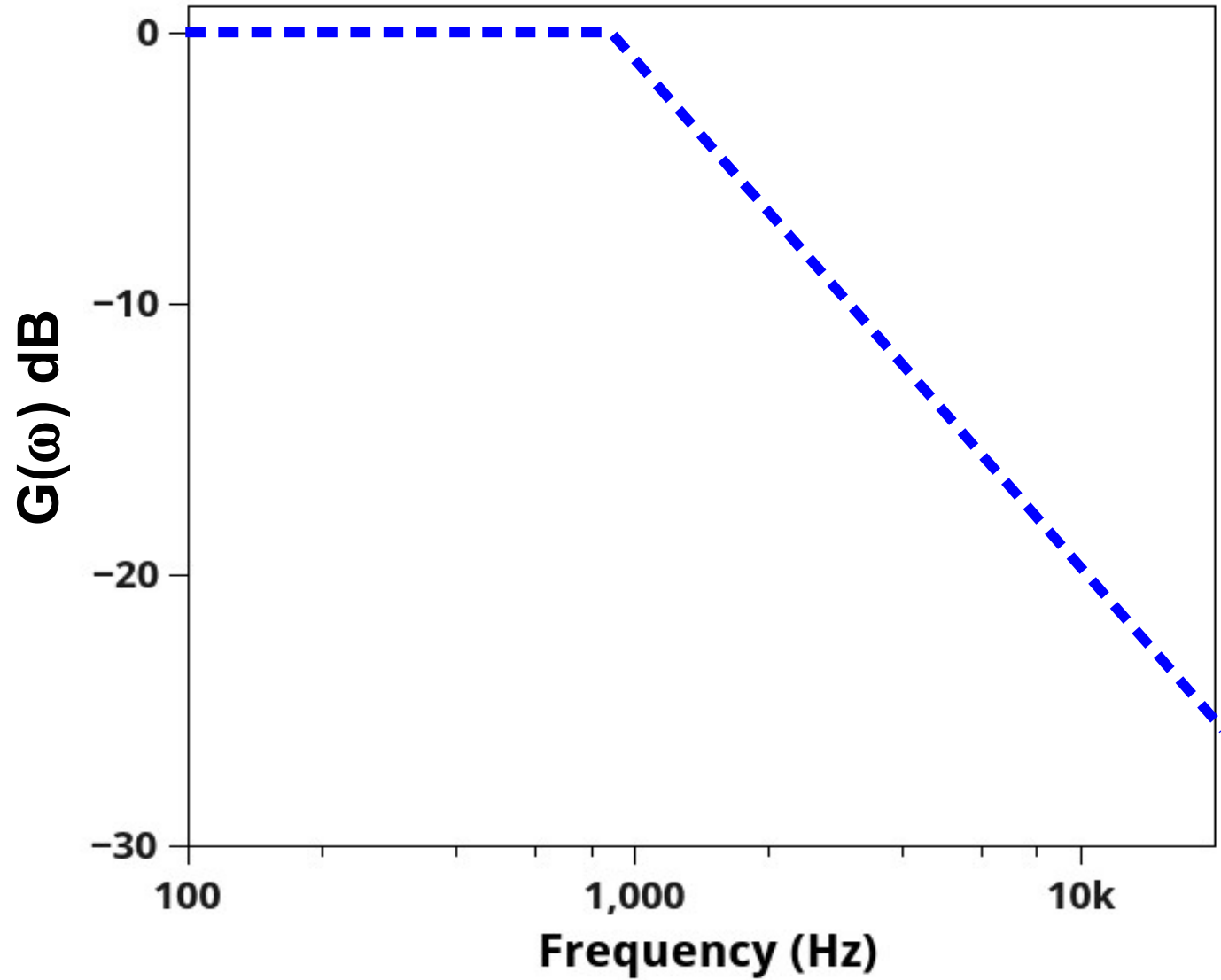
$$\frac{V_{OUT}}{V_{IN}} = -\frac{R2}{R1} \left( \frac{1}{1 + j\omega R2 C1} \right)$$

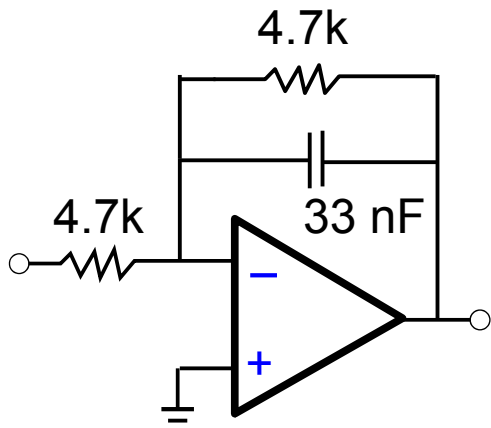
Pole in denominator



1-pole: 1 kHz

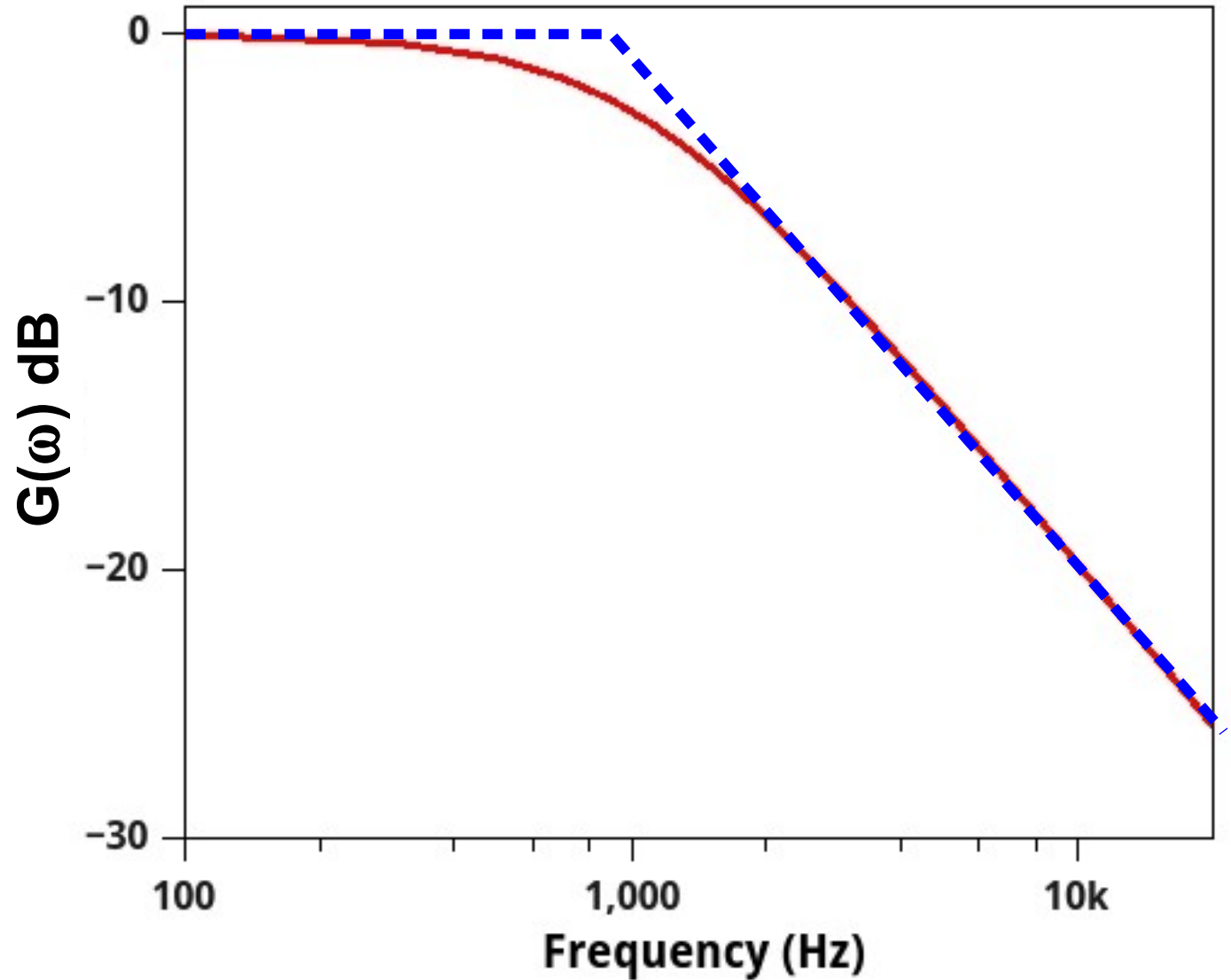
Pole at 1 kHz: -20 dB/decade



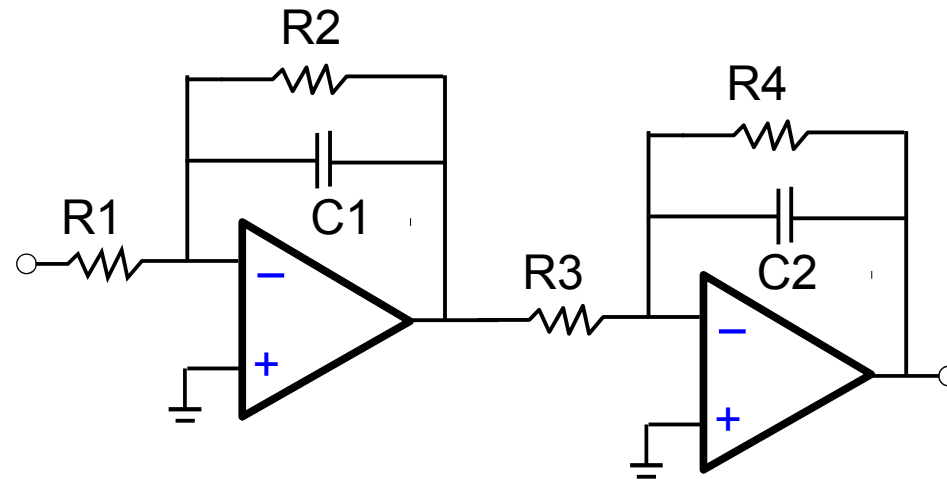


1-pole: 1 kHz

Red curve: Full-model calculation

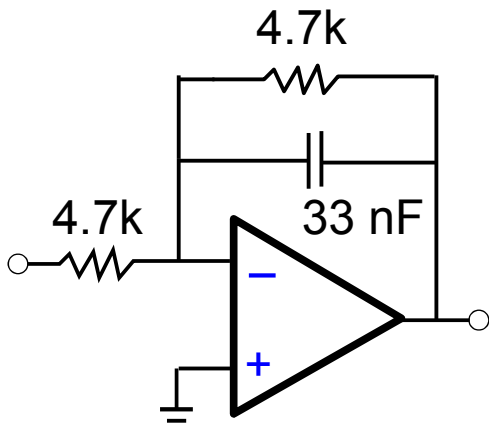


# Example: Low-pass filter

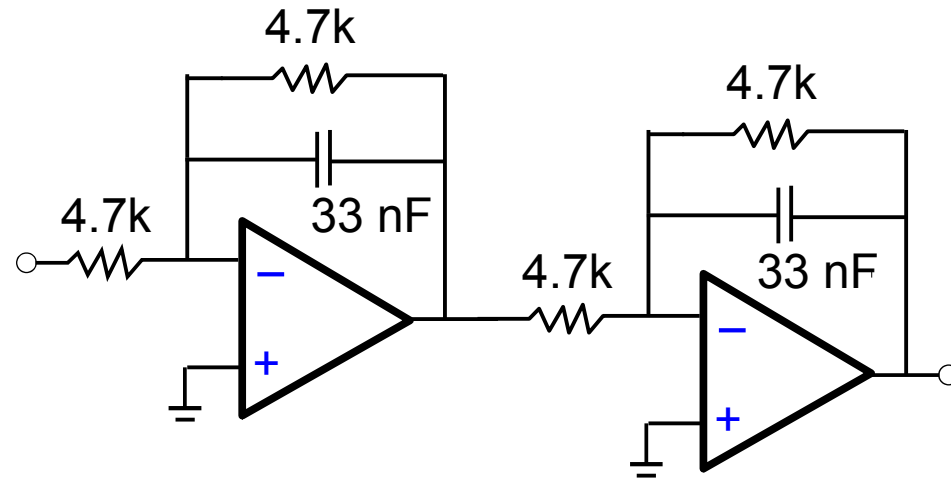


$$\frac{V_{OUT}}{V_{IN}} = \frac{R_2}{R_1} \underbrace{\left( \frac{1}{1 + j\omega R_2 C_1} \right)}_{\text{1st pole}} \frac{R_4}{R_3} \underbrace{\left( \frac{1}{1 + j\omega R_4 C_2} \right)}_{\text{2nd pole}}$$



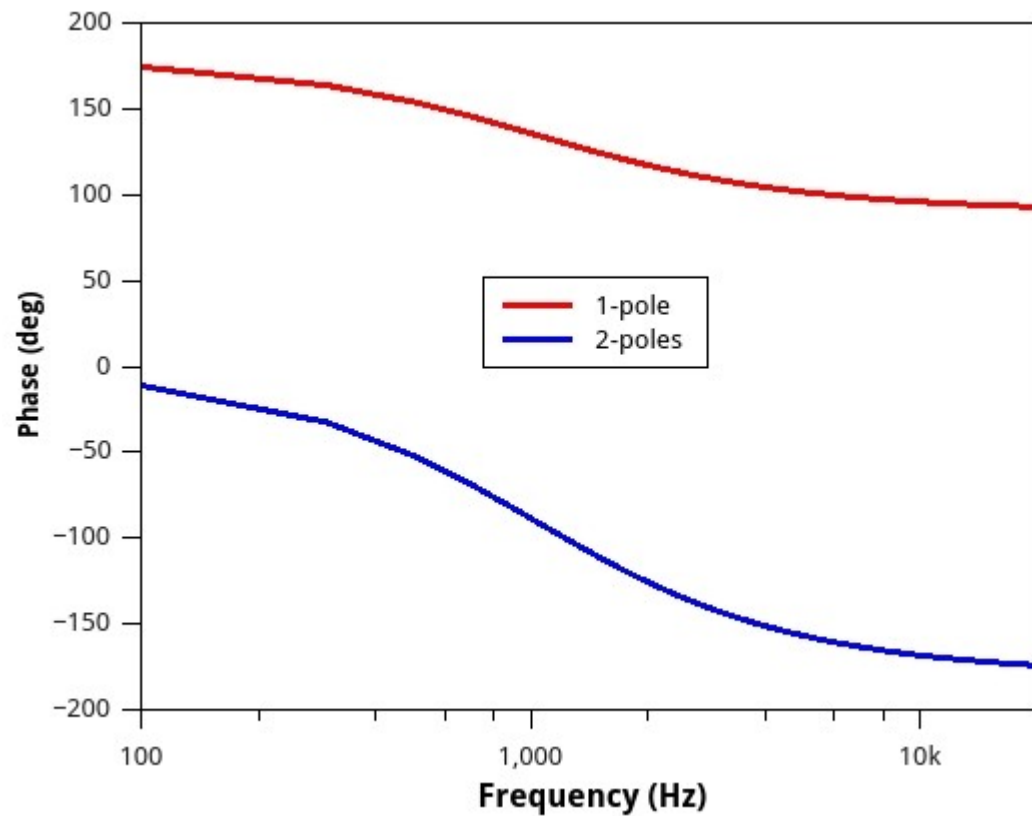
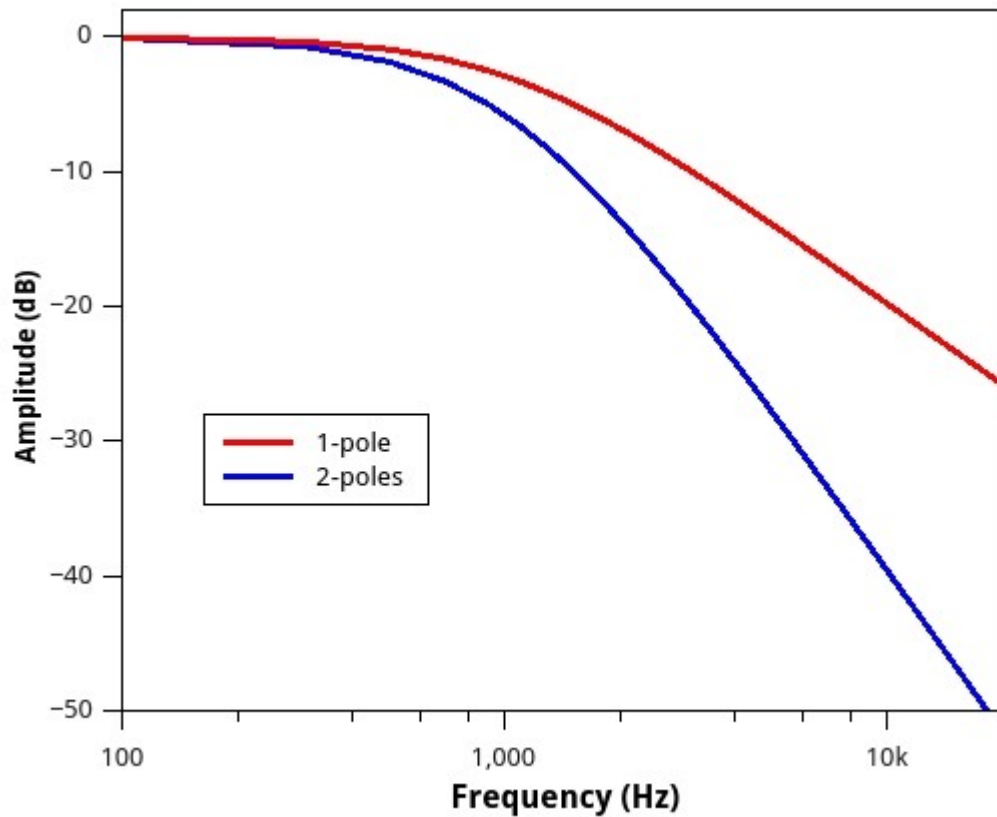


**1-pole: 1 kHz**

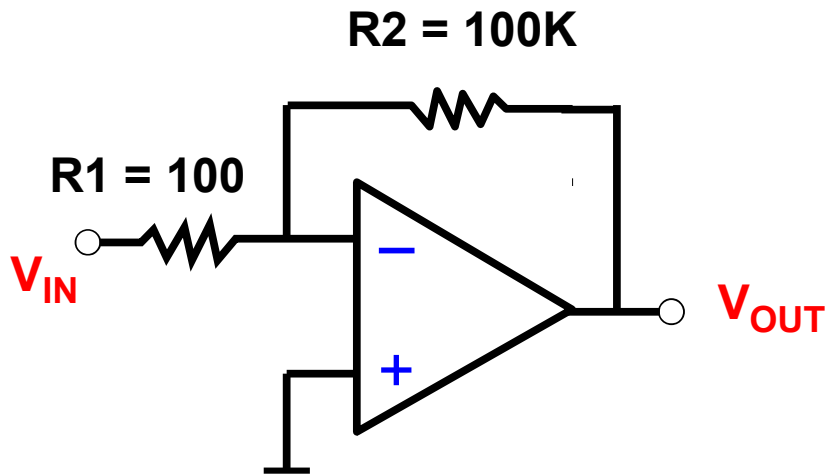


**1st-pole: 1 kHz**

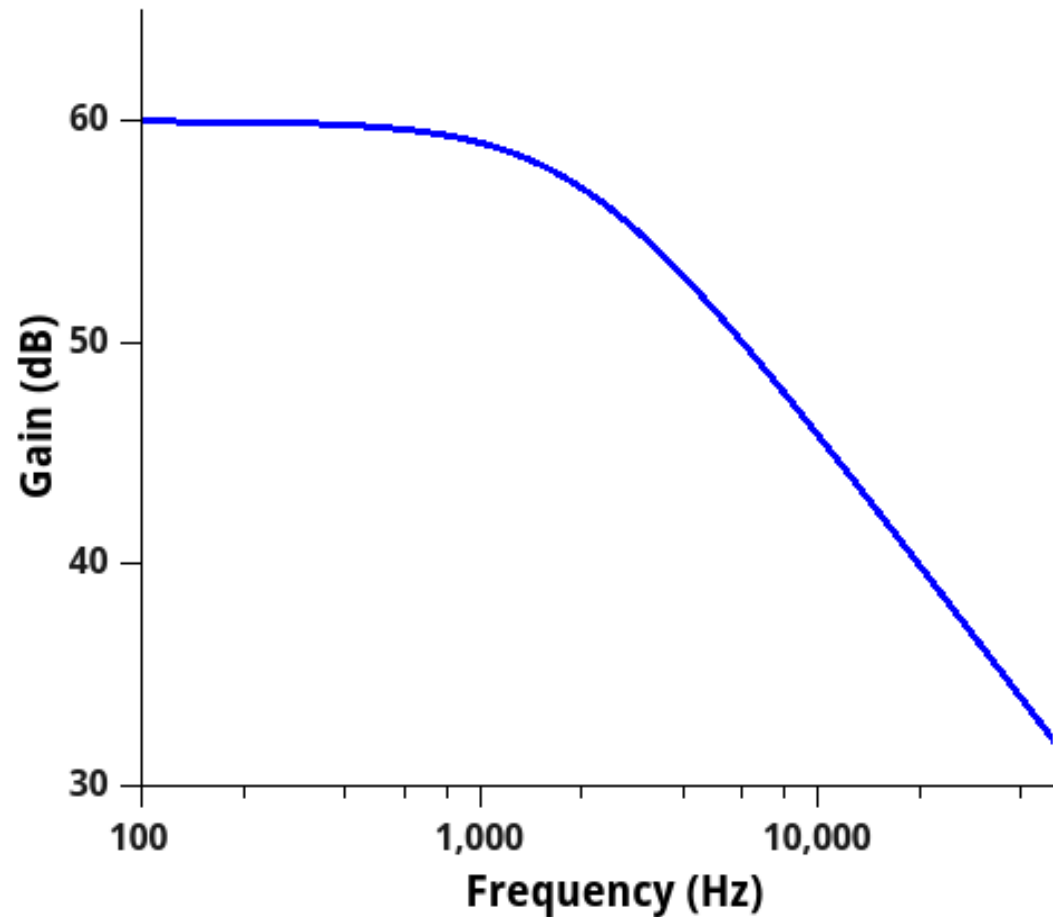
**2nd-pole: 1 kHz**



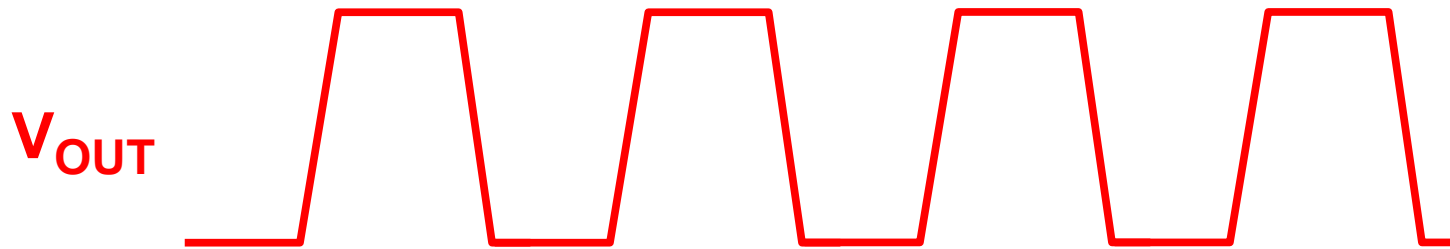
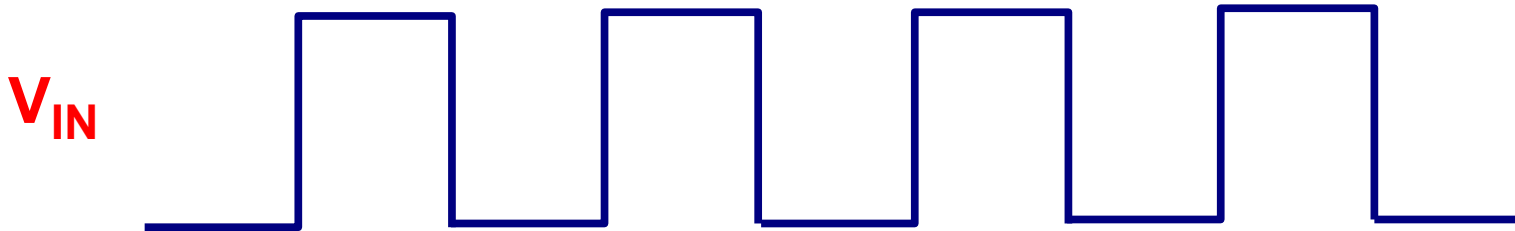
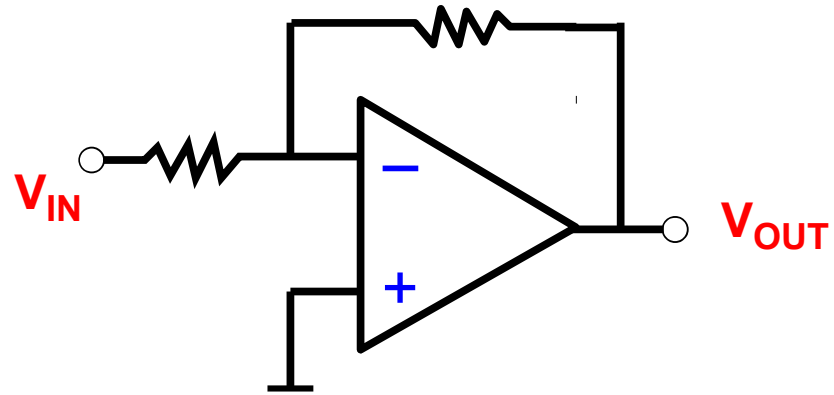
# NON-IDEAL BEHAVIOR: GAIN-BANDWIDTH PRODUCT



$$\text{GAIN} = -\frac{R2}{R1} = 60 \text{ dB}$$



# NON-IDEAL BEHAVIOR: SLEWING



**SLOPE:**  
 $V/\mu s$