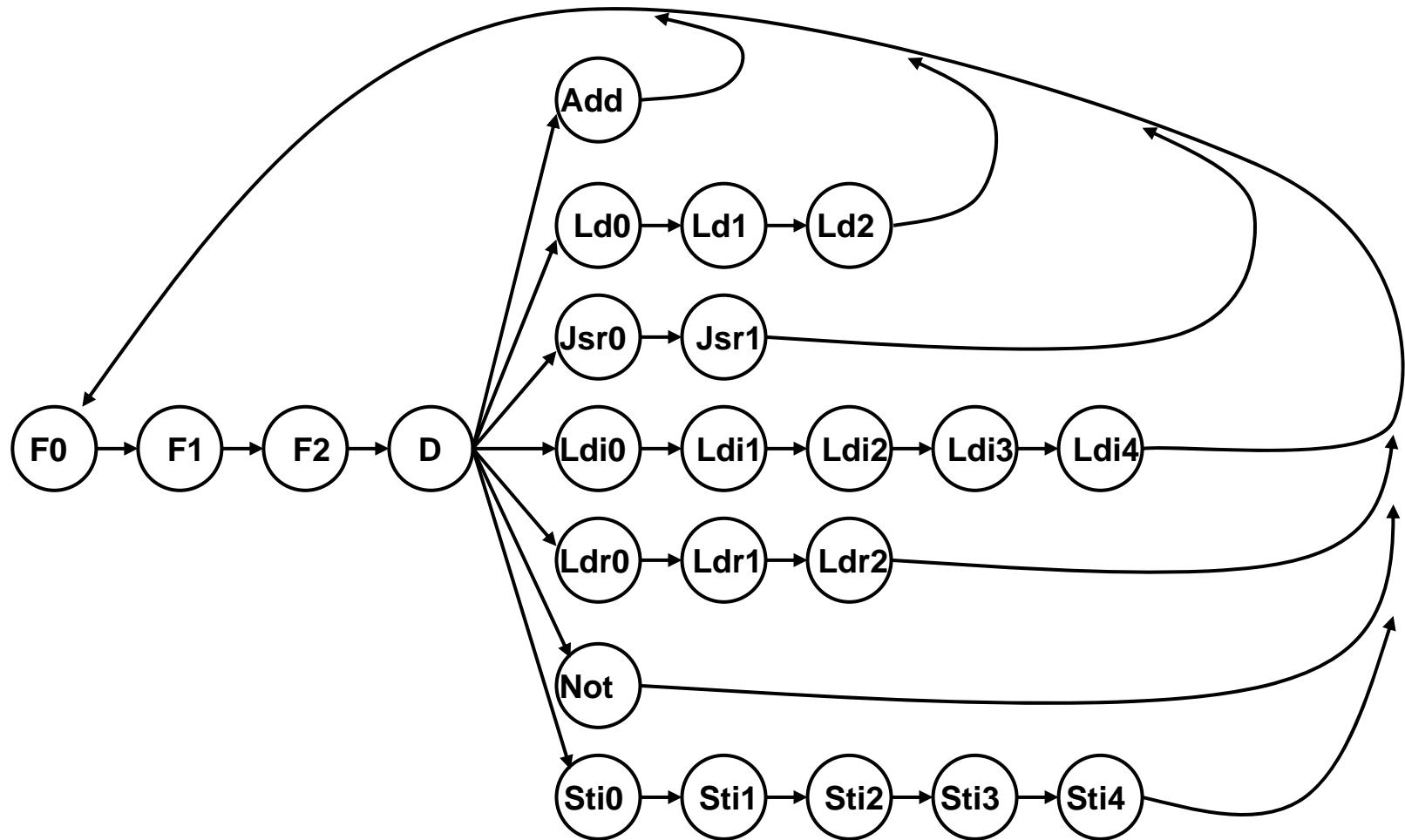
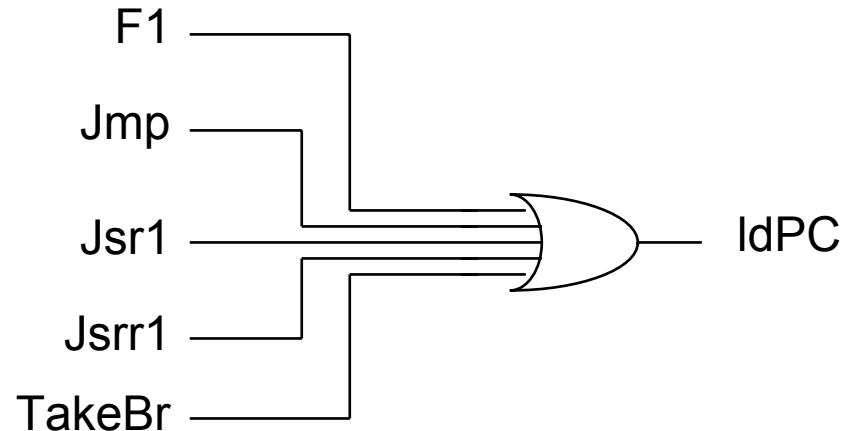


Microprogrammed Control

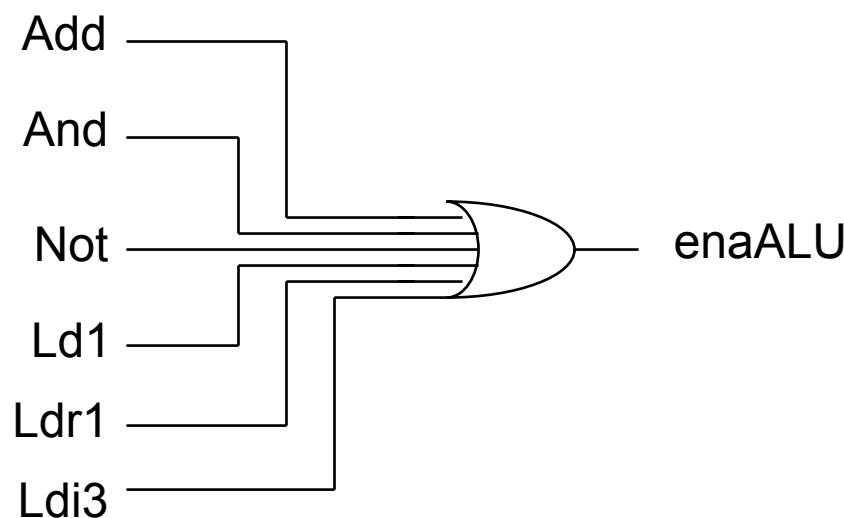
Sample Control Unit FSM



Sample Output Forming Logic



One-hot encoding leads
to pretty simple OFL!



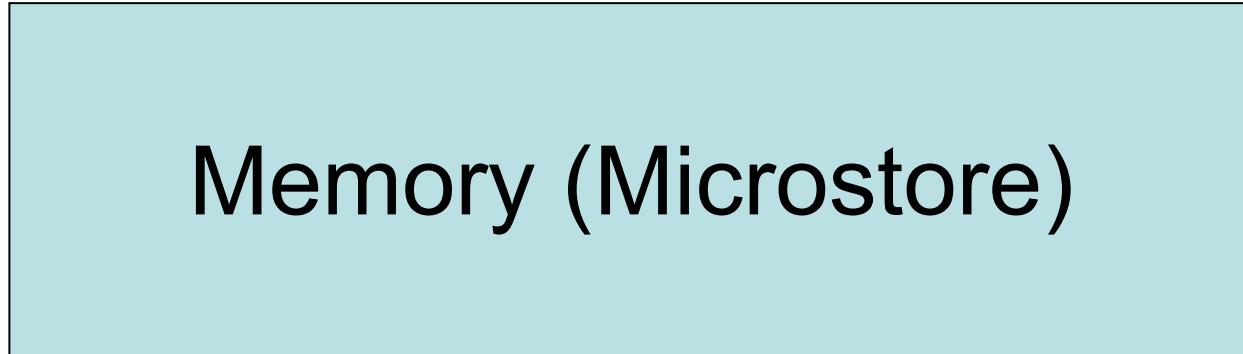
The Control Unit

- The LC-3 control lecture discussed a hard-wired approach to controller design
 - The functionality is fixed after the design
- **Microprogrammed controllers** allow functionality to be easily changed
 - Instructions can be added or changed with only minor changes to the *microcode*

Microprogrammed Control

An internal memory called the **control store** (or Microstore) contains the settings for all of the control signals for all.

Each memory location contains one complete set of control values.

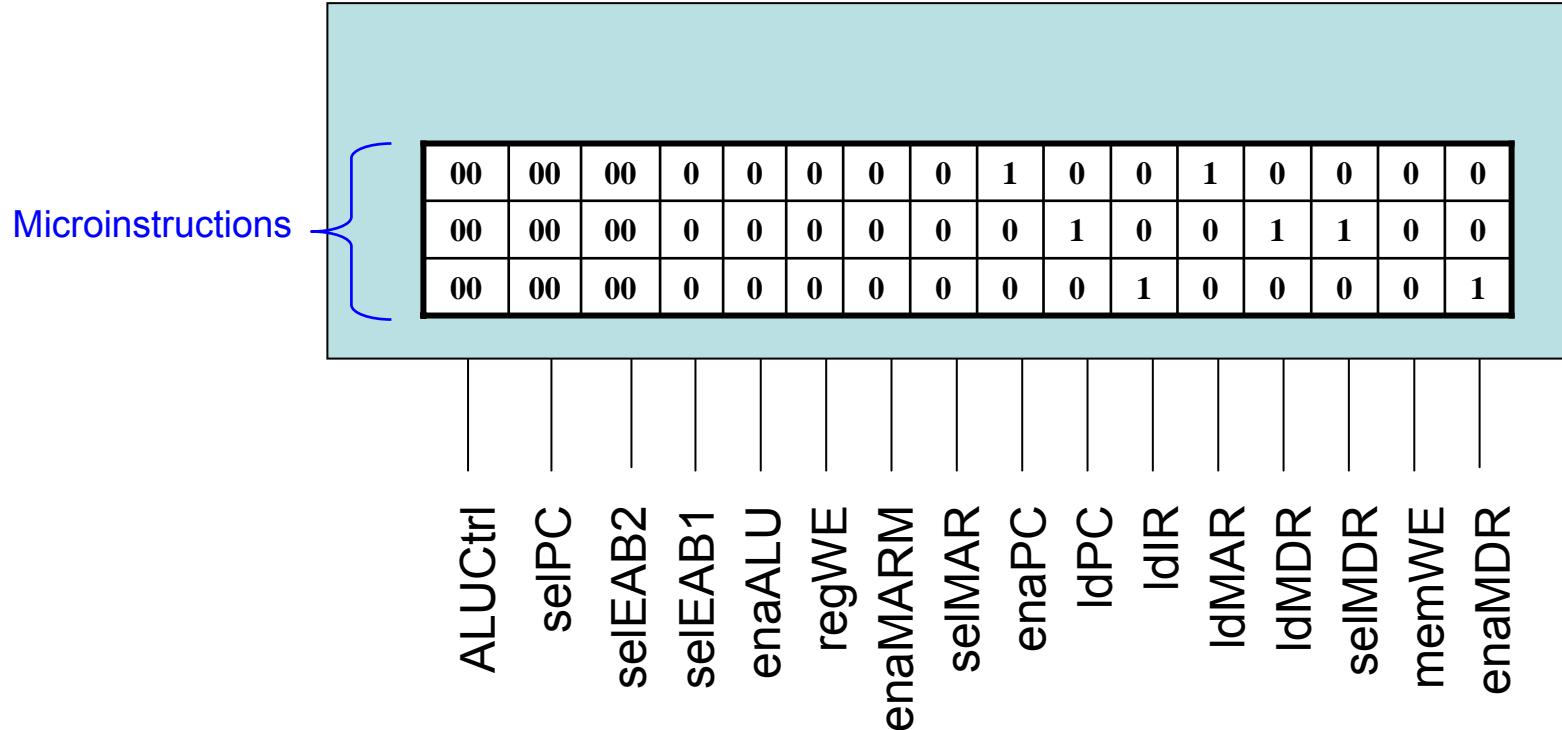


ALUCtrl selPC selEAB2 selEAB1 enaALU regWE enaMAR
selMAR enaPC ldPC ldIR ldMAR ldMDR selMDR
memWE enaMDR

Microprogrammed Control

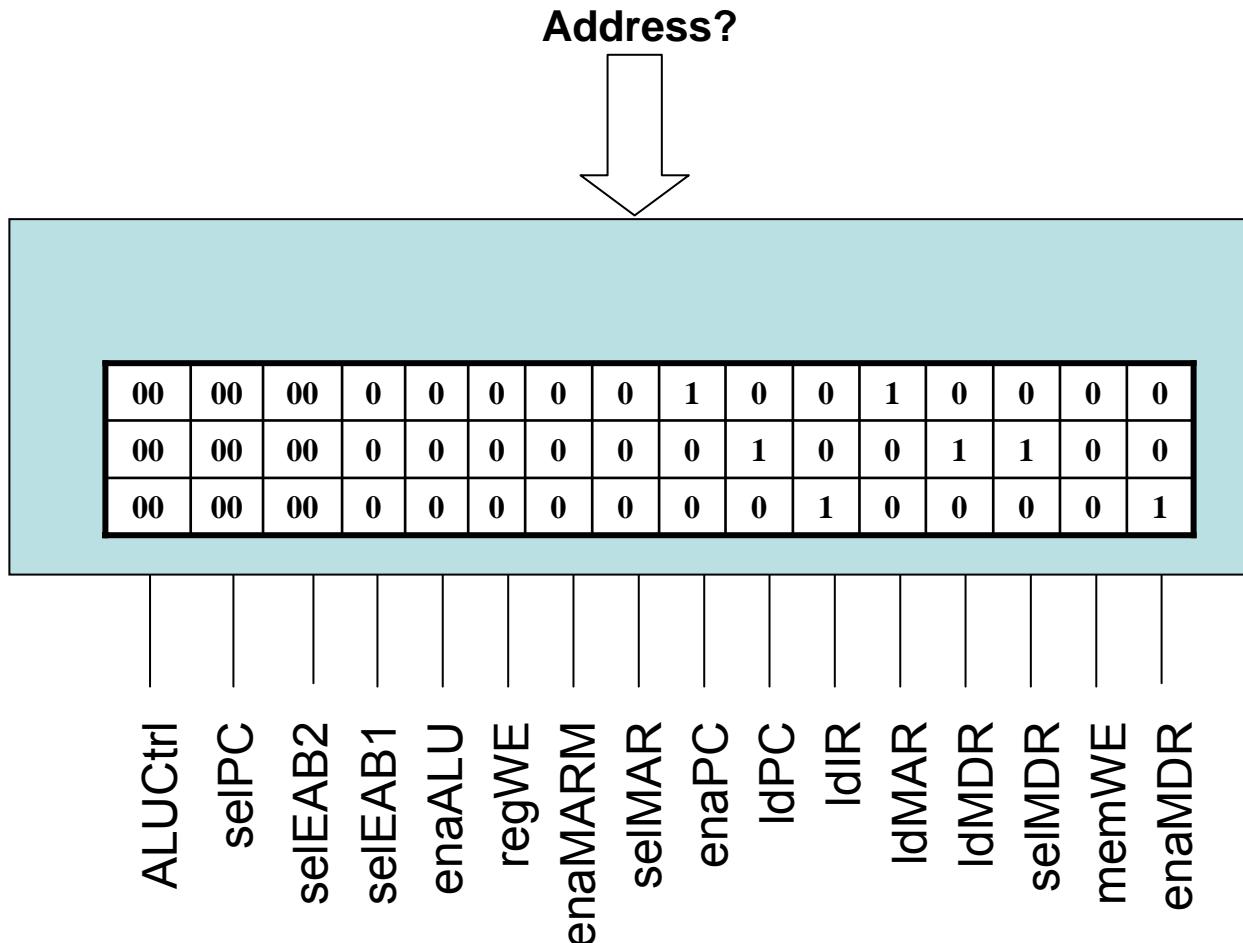
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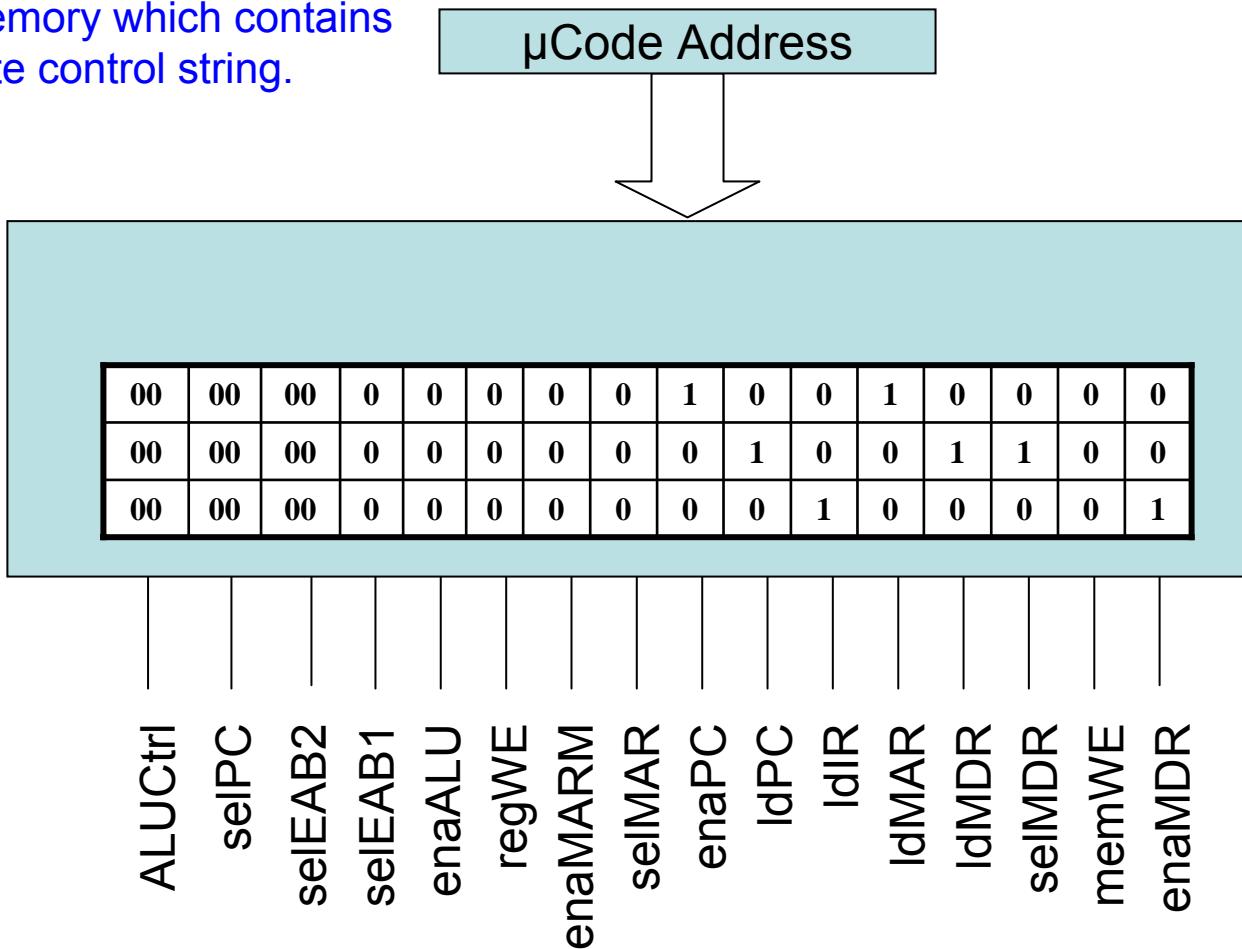
Microprogrammed Control

How do you determine which control string to use?

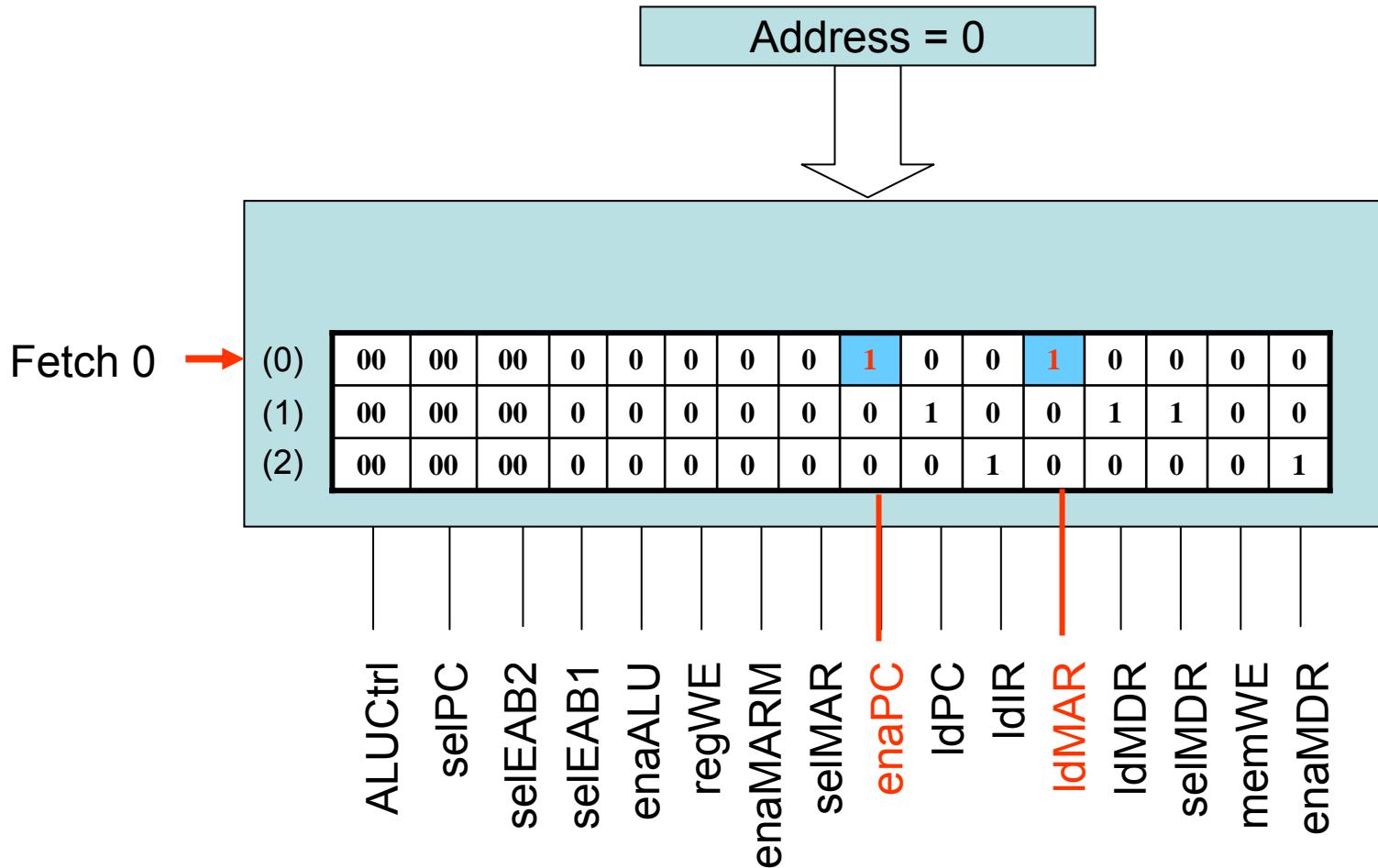


Microprogrammed Control

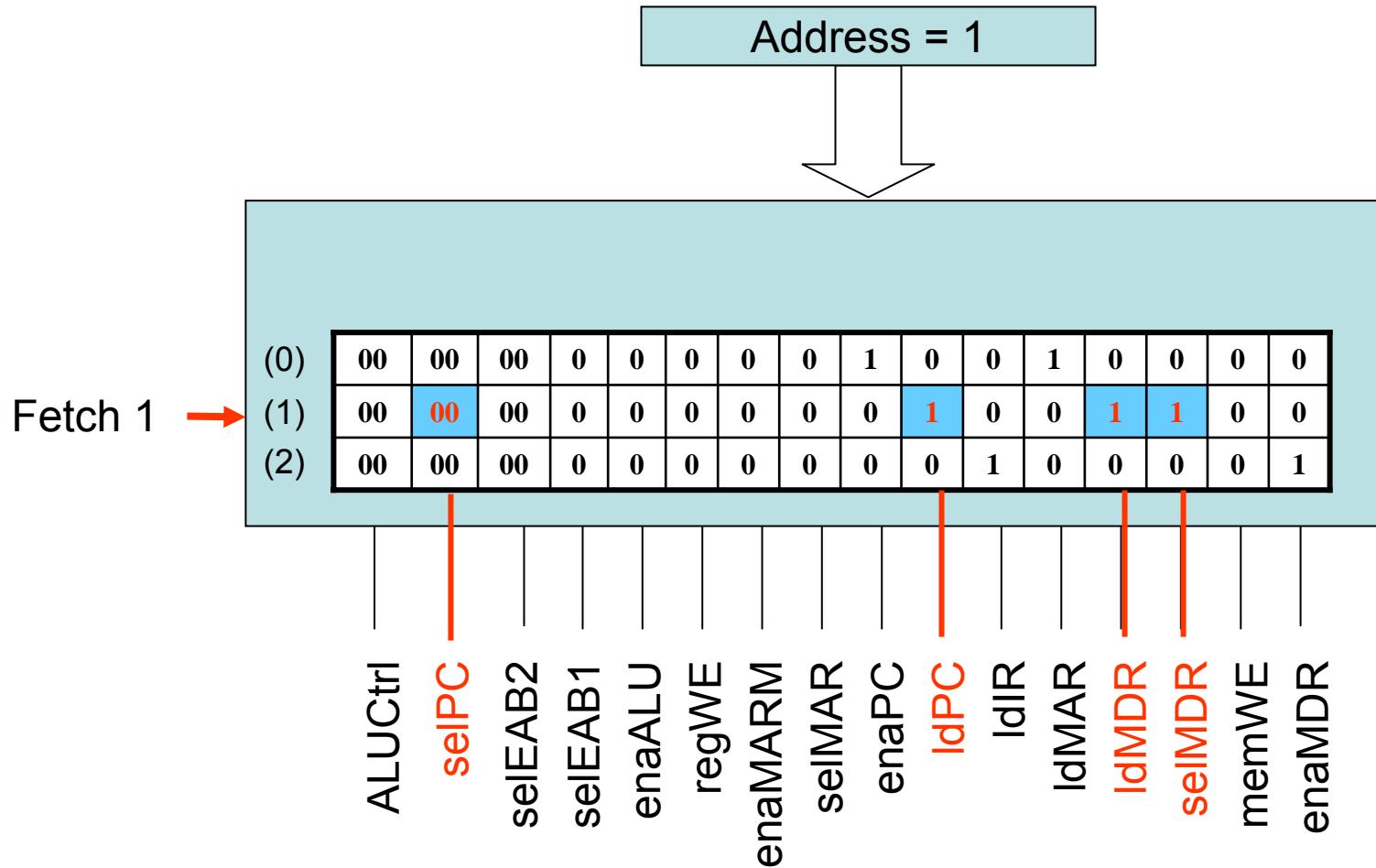
Use a register to select the address in memory which contains the appropriate control string.



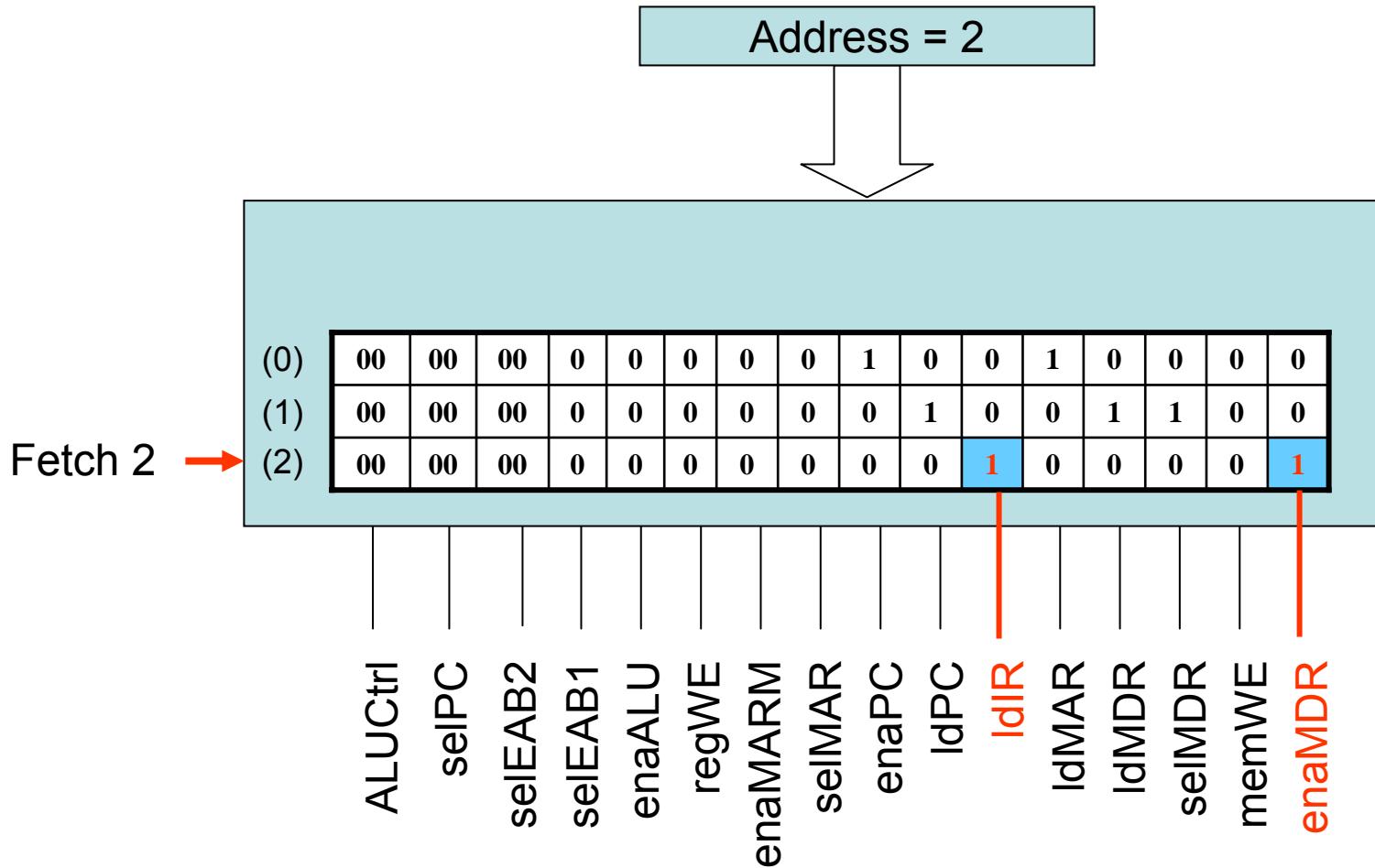
Microprogrammed Control



Microprogrammed Control

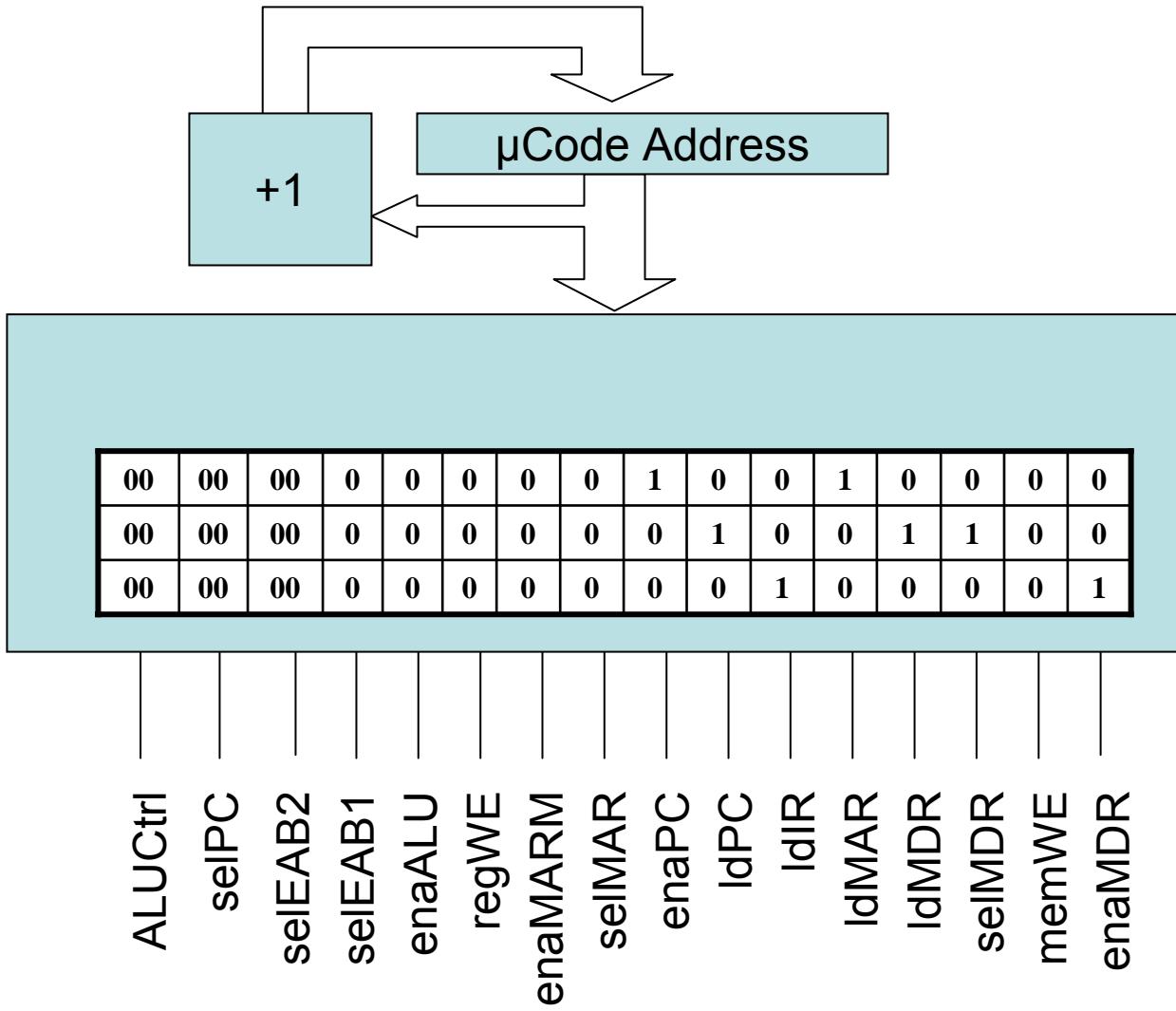


Microprogrammed Control

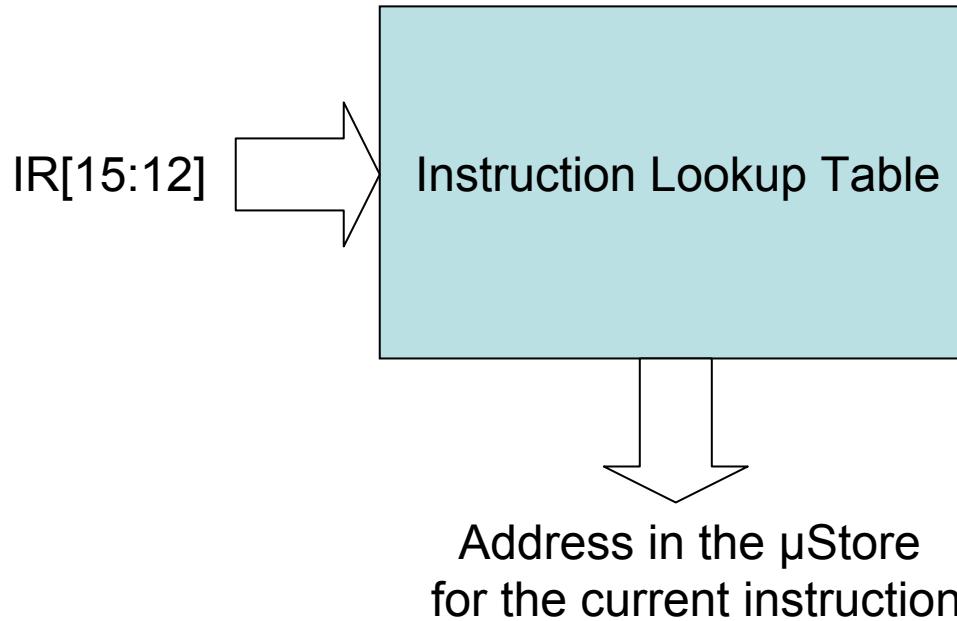


Microprogrammed Control

Use incrementer to get sequential control strings.



Decode

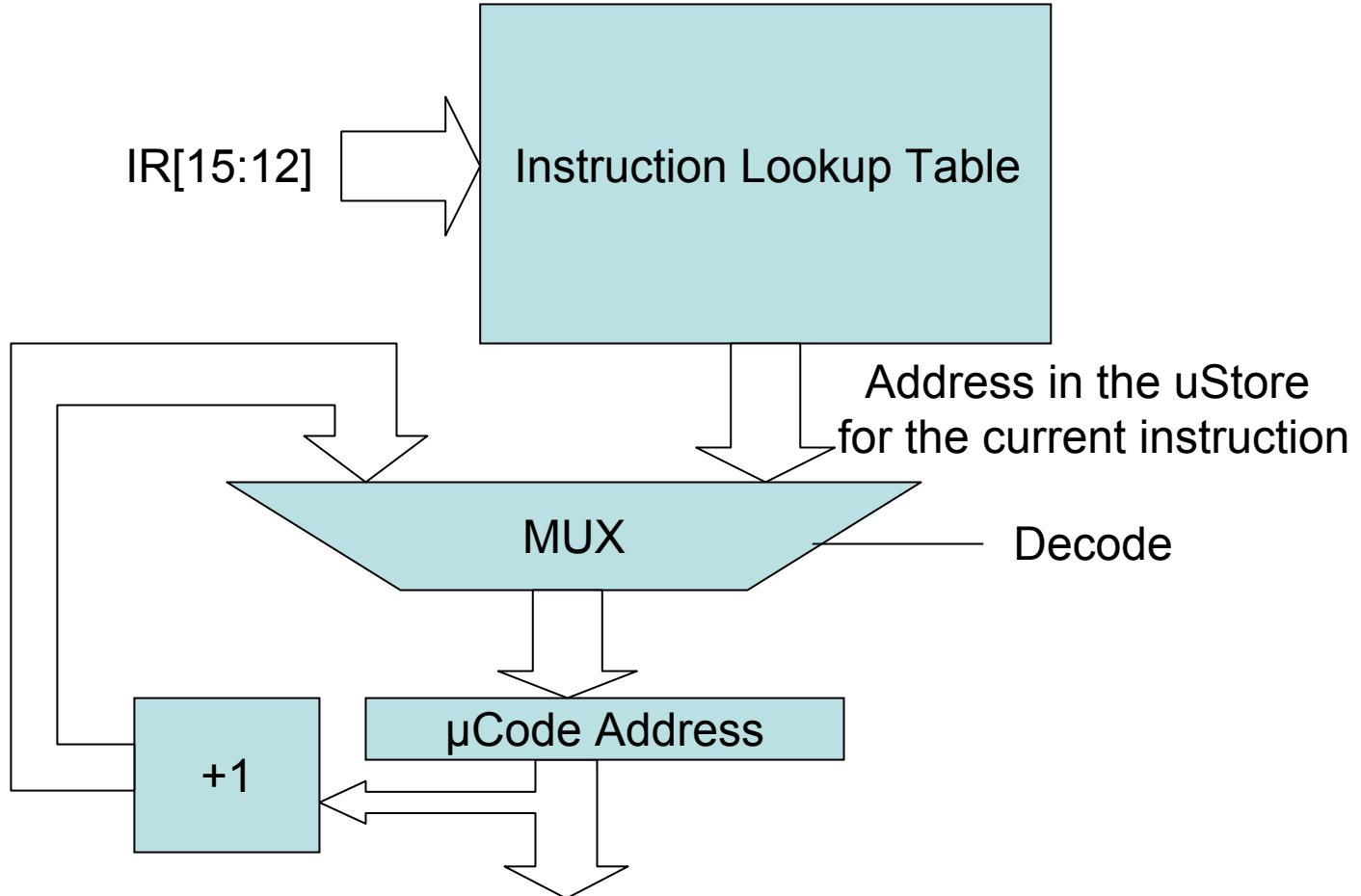


Use a lookup table to get to the appropriate control strings after an instruction has been loaded into the Instruction Register.

This occurs in the Decode stage of the instruction.

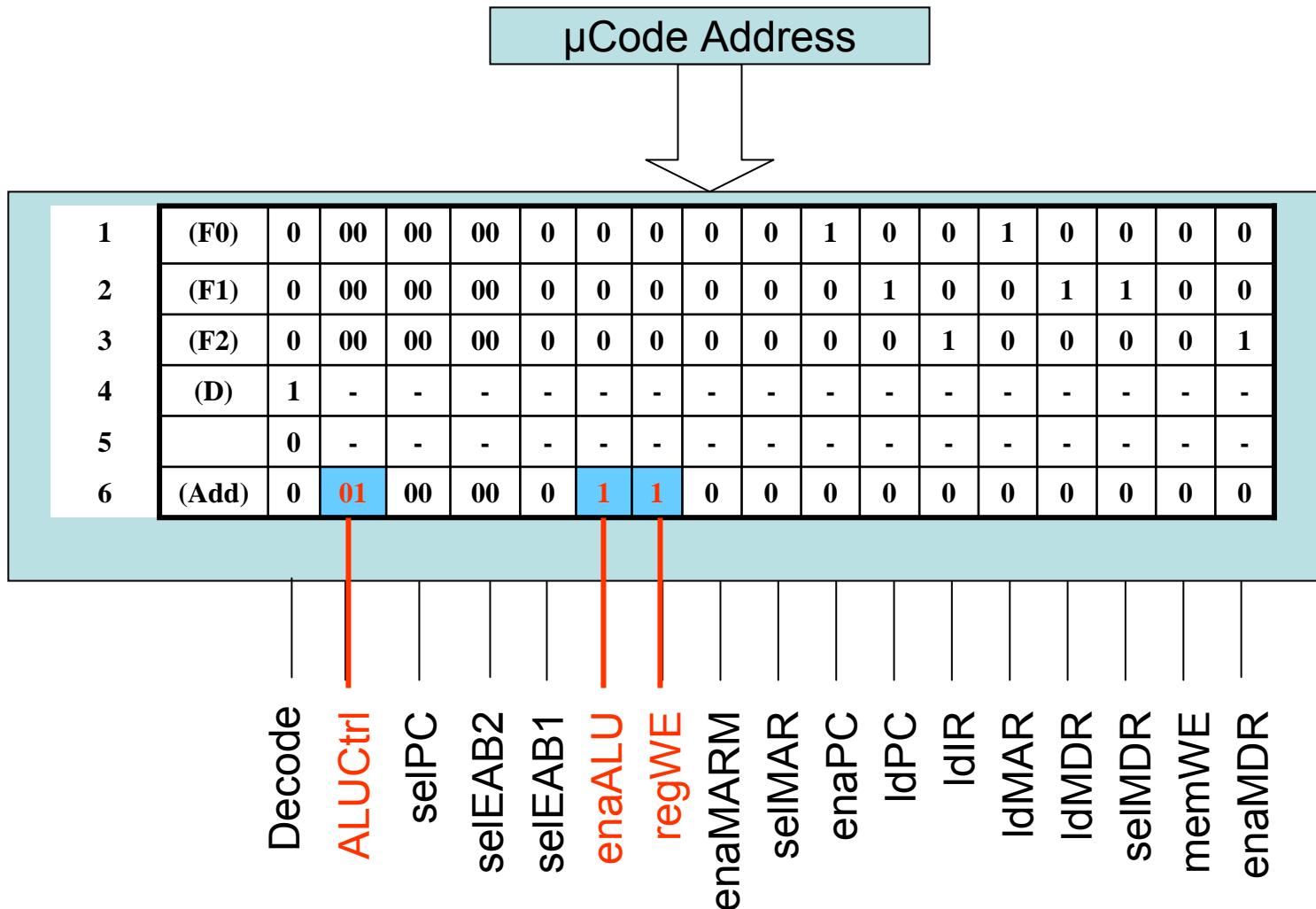
Decode

Use a MUX to select between the sources for the μ Code Address.



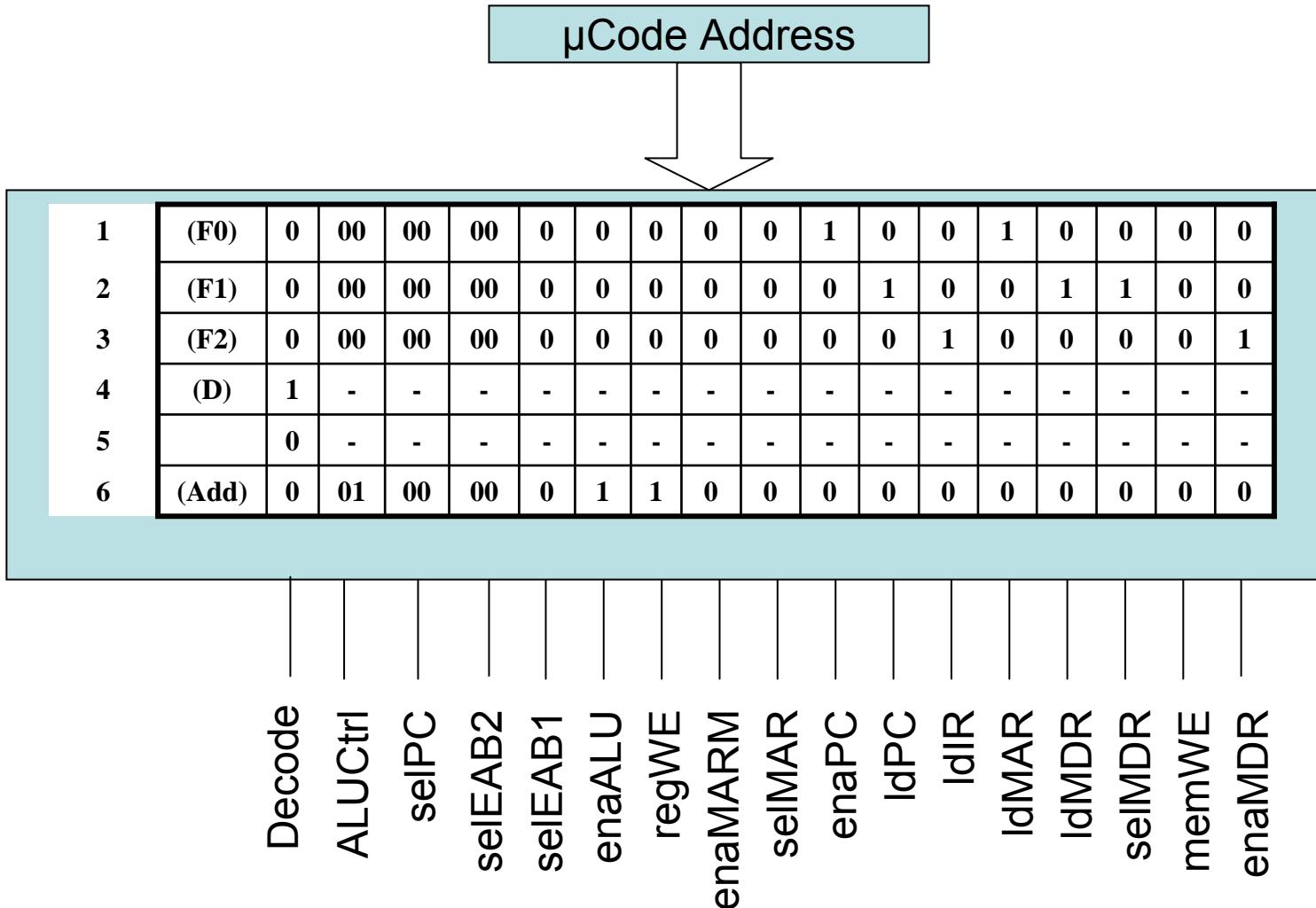
Microprogrammed Control

Instruction Execution



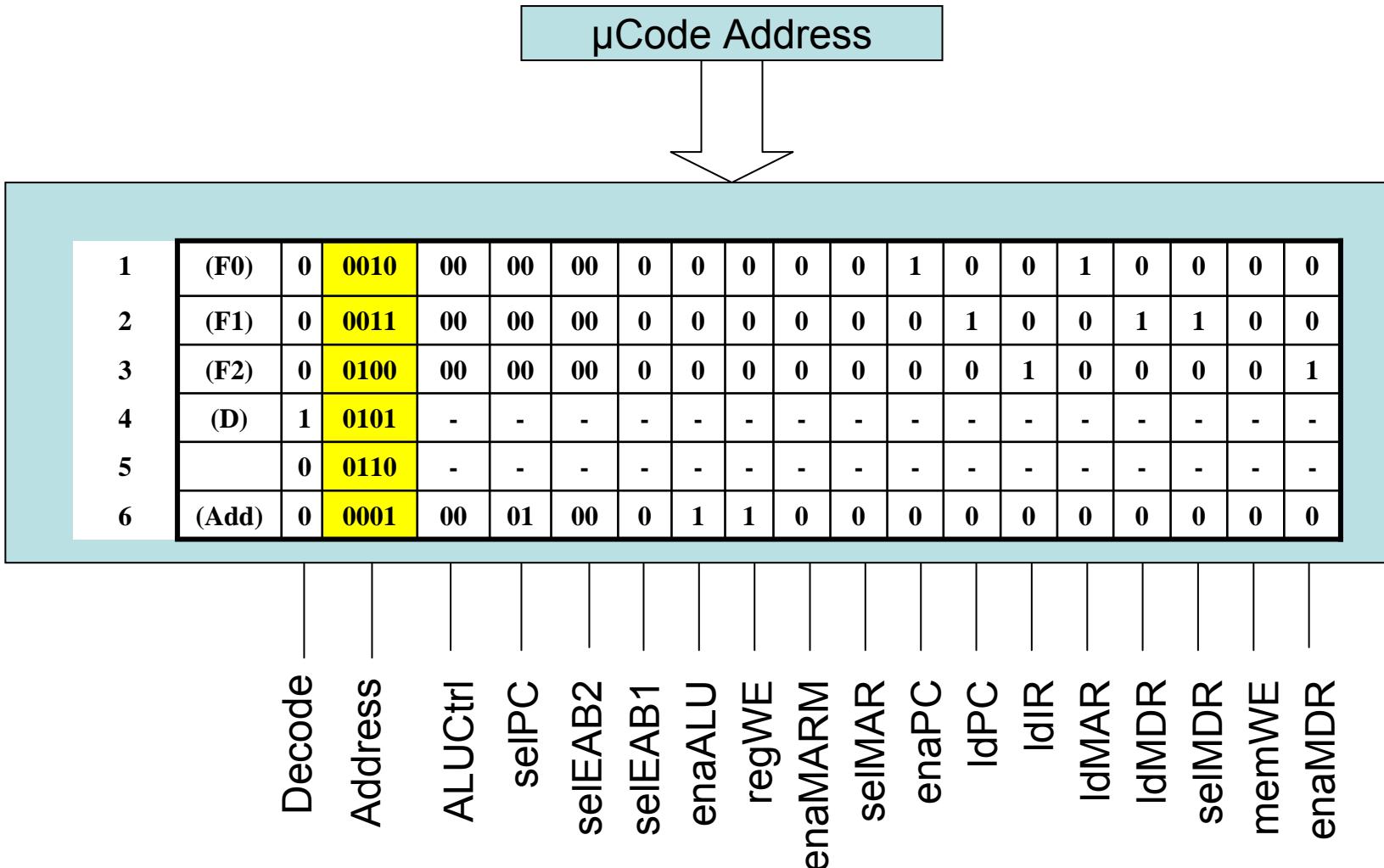
Microprogrammed Control

How to return to the fetch cycle?



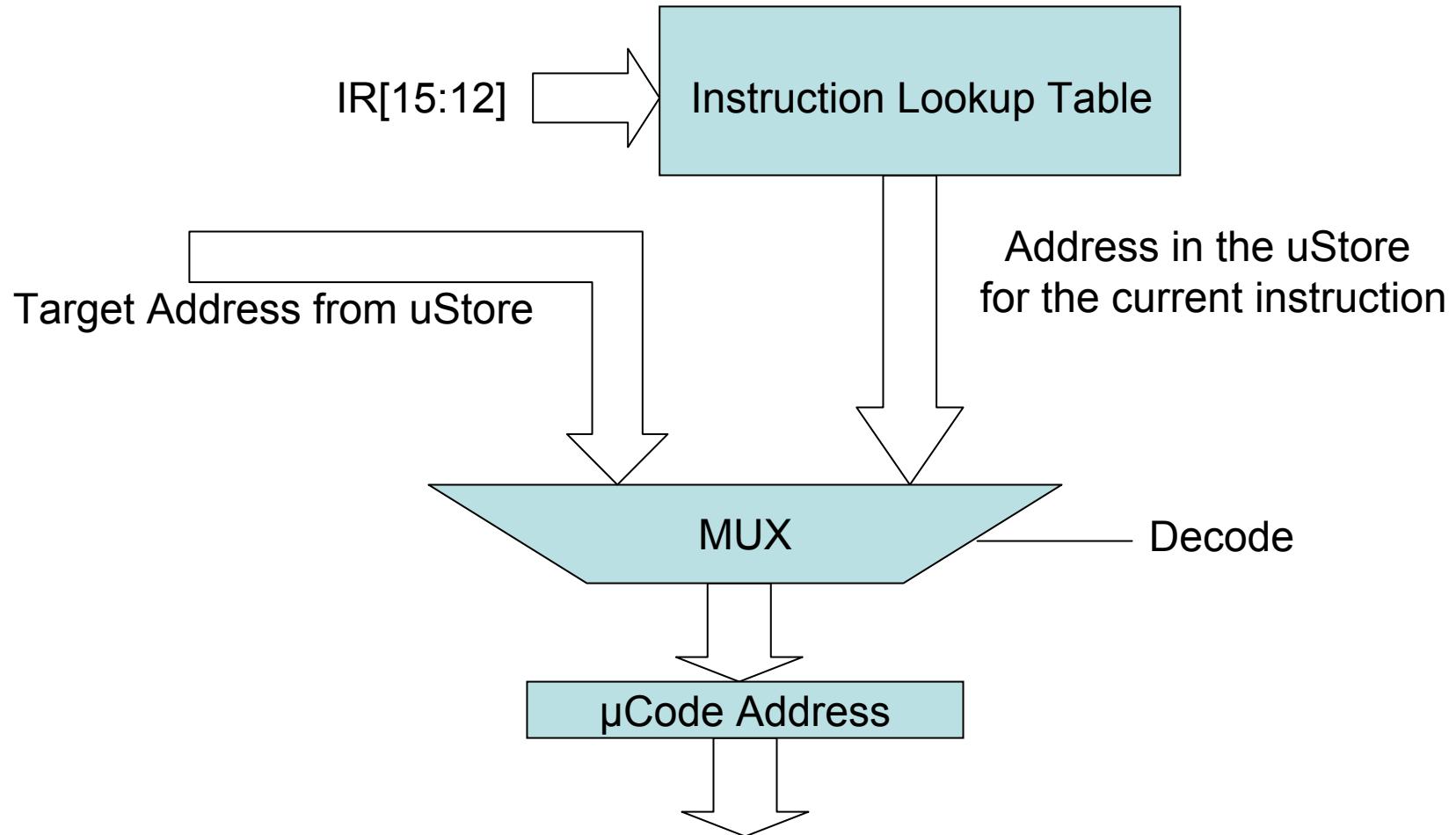
Microprogrammed Control

Use a special field to designate the next address which should be executed!



Jump to a New µCode Address

Because of the Target Address field, the incrementer is no longer needed.



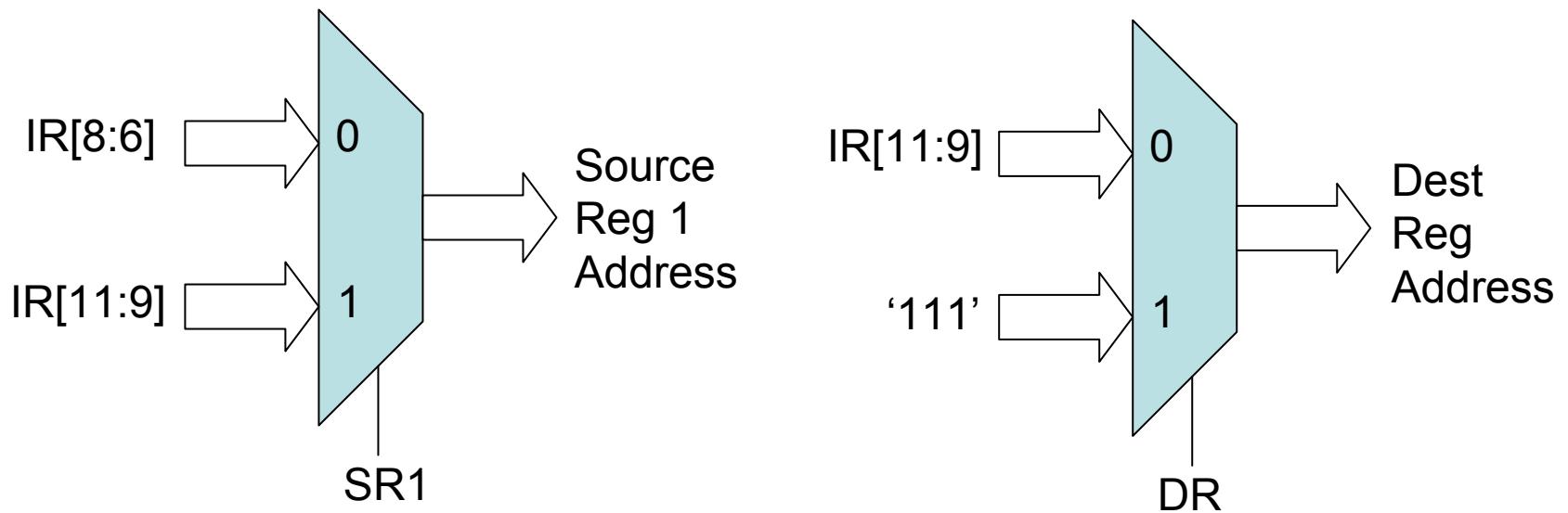
Selecting Operand and Destination Register Addresses

ADD	0001	DR	SR1	0	00	SR2
ADD	0001	DR	SR1	1		imm5
AND	0101	DR	SR1	0	00	SR2
AND	0101	DR	SR1	1		imm5
NOT	1001	DR	SR		111111	
BR	0000	n	z	p		PCoffset9
JMP	1100	0	00	BaseR		000000
JSR	0100	1			PCoffset11	
JSRR	0100	0	00	BaseR		000000
RET	1100	0	00	111		000000

LD	0010	DR		PCoffset9
LDI	1010	DR		PCoffset9
LDR	0110	DR	BaseR	offset6
LEA	1110	DR		PCoffset9
ST	0011	SR		PCoffset9
STI	1011	SR		PCoffset9
STR	0111	SR	BaseR	offset6
TRAP	1111	0000		trapvect8
RTI	1000			00000000000000
reserved	1101			

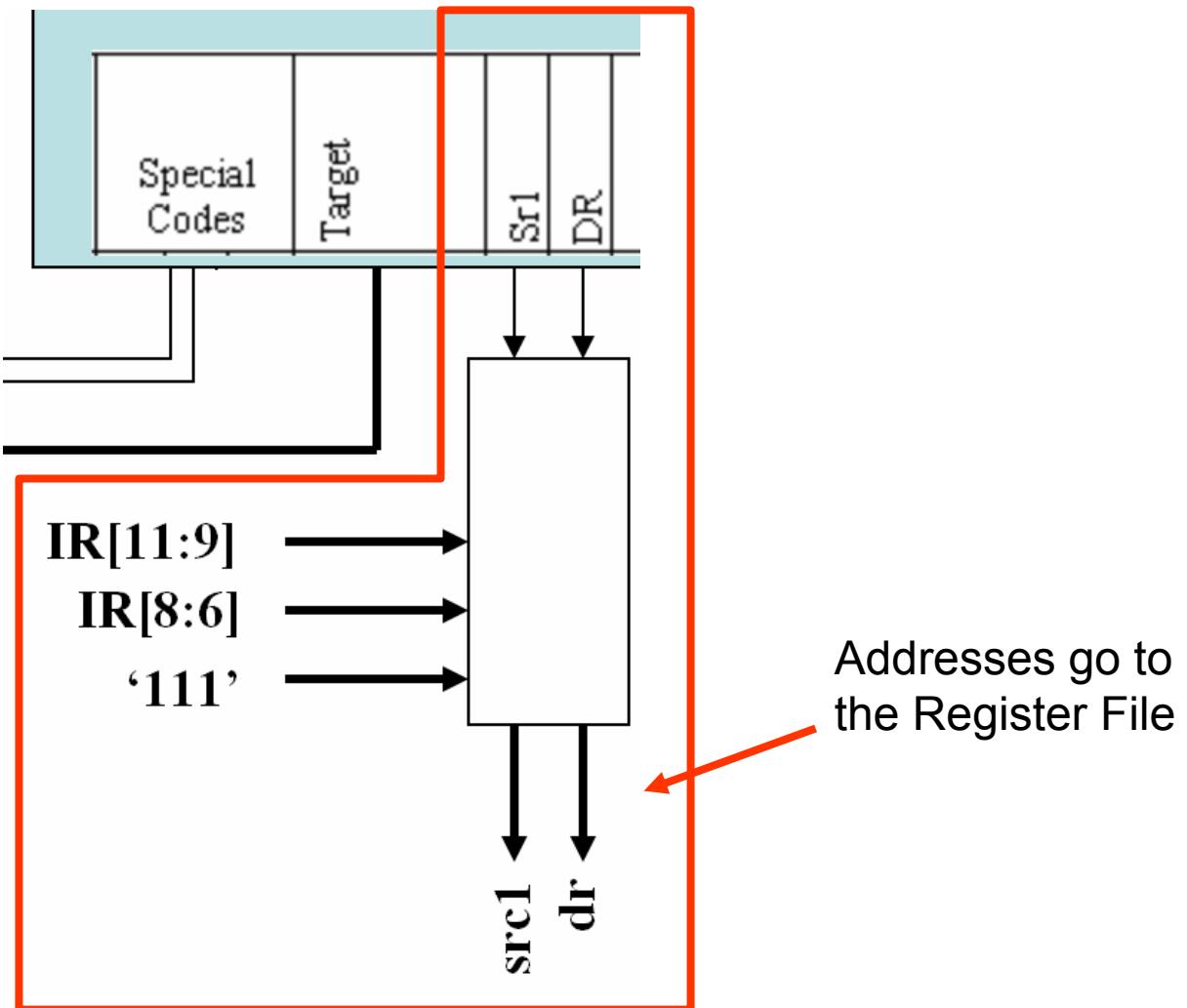
Selecting Operand and Destination Register Addresses

Two more control signals are required in the μ Store: SR1 and DR. These signals select the source for the register addresses.



Selecting Operand and Destination Register Addresses

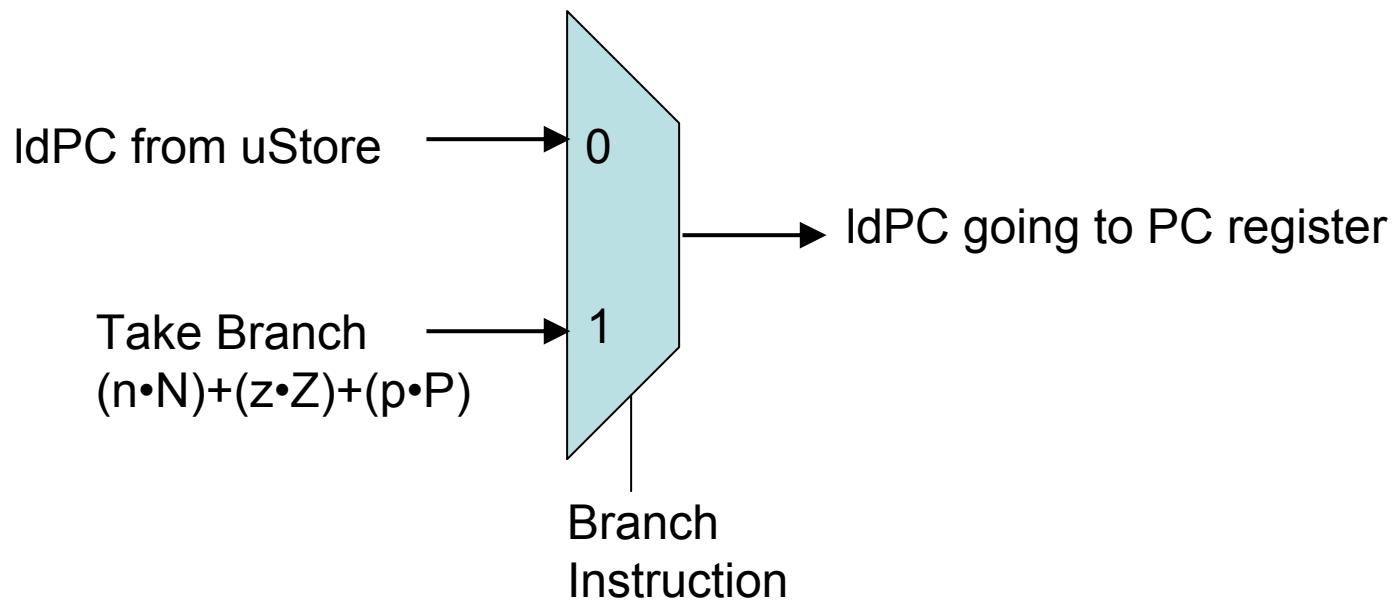
00: --
01: decode
10: branch
11: JSRcond



Selecting Load Program Counter Sources

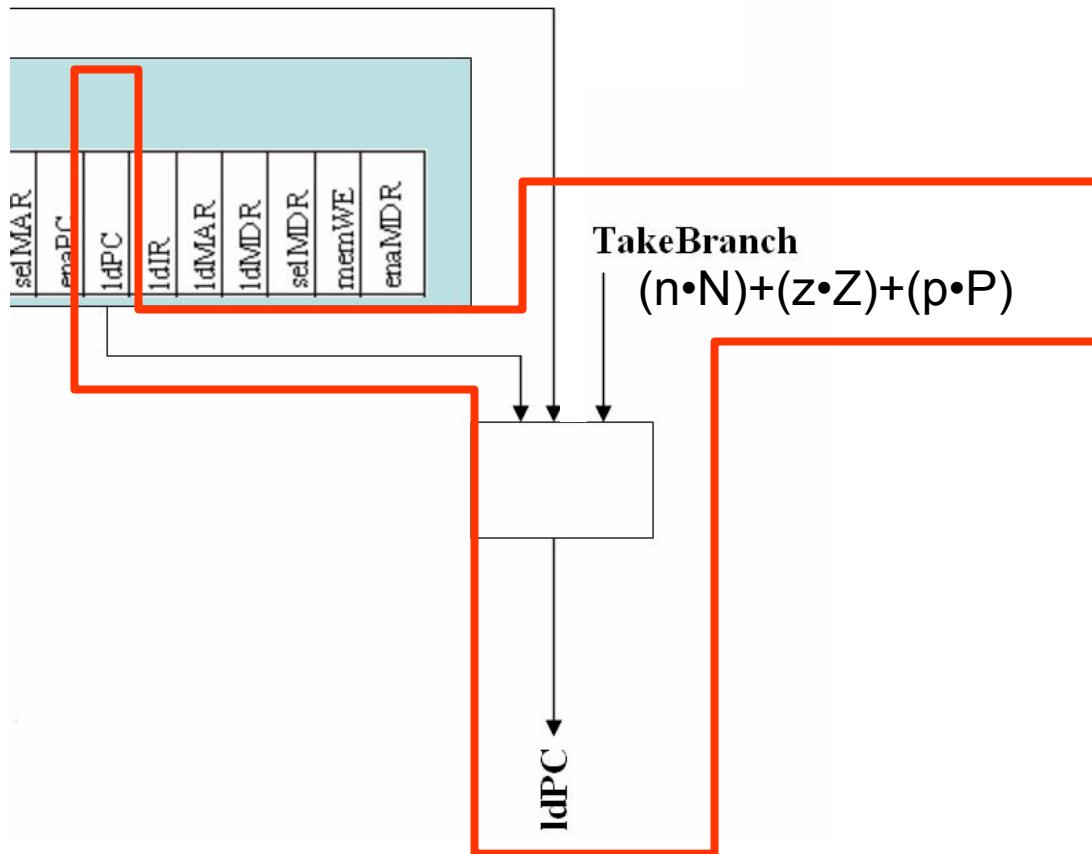
For a Branch instruction, loading of the PC depends upon the N, Z and P register flags and the n, z and p bits in the instruction.

Another control signal is needed to select the source for the load PC control signal.



Selecting Load Program Counter Sources

'Special Code' bit for branch instruction



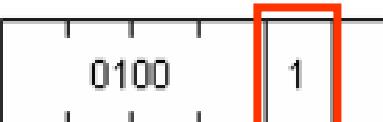
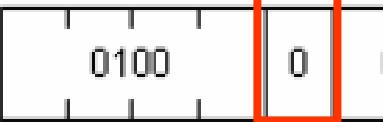
Selecting Jump Subroutine MUX control sources

The two types of JSR instructions use different control signals but share the same opcode.

JSR	clock1	$R7 \leftarrow PC$	$enaPC \leftarrow 1$
			$DR \leftarrow 7$
			$regWE \leftarrow 1$
	clock2	$PC \leftarrow EAddr$	$selEAB1 \leftarrow 0$
			$selEAB2 \leftarrow 11$
			$selPC \leftarrow 01$
			$ldPC \leftarrow 1$
JSRR	clock1	$R7 \leftarrow PC$	$enaPC \leftarrow 1$
			$DR \leftarrow 7$
			$regWE \leftarrow 1$
	clock2	$PC \leftarrow EAddr$	$selEAB1 \leftarrow 1$
			$selEAB2 \leftarrow 00$
			$selPC \leftarrow 01$
			$ldPC \leftarrow 1$

Selecting Jump Subroutine MUX control sources

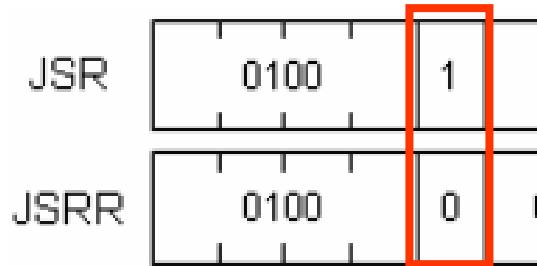
Use IR[11] to distinguish between the two forms of JSR.

JSR	
JSRR	

JSR	clock1 R7 \leftarrow PC	enaPC \leftarrow 1 DR \leftarrow 7 regWE \leftarrow 1 selEAB1 \leftarrow 0 selEAB2 \leftarrow 11 selPC \leftarrow 01 ldPC \leftarrow 1
	clock2 PC \leftarrow EAddr	
JSRR	clock1 R7 \leftarrow PC	enaPC \leftarrow 1 DR \leftarrow 7 regWE \leftarrow 1 selEAB1 \leftarrow 1 selEAB2 \leftarrow 00 selPC \leftarrow 01 ldPC \leftarrow 1
	clock2 PC \leftarrow EAddr	

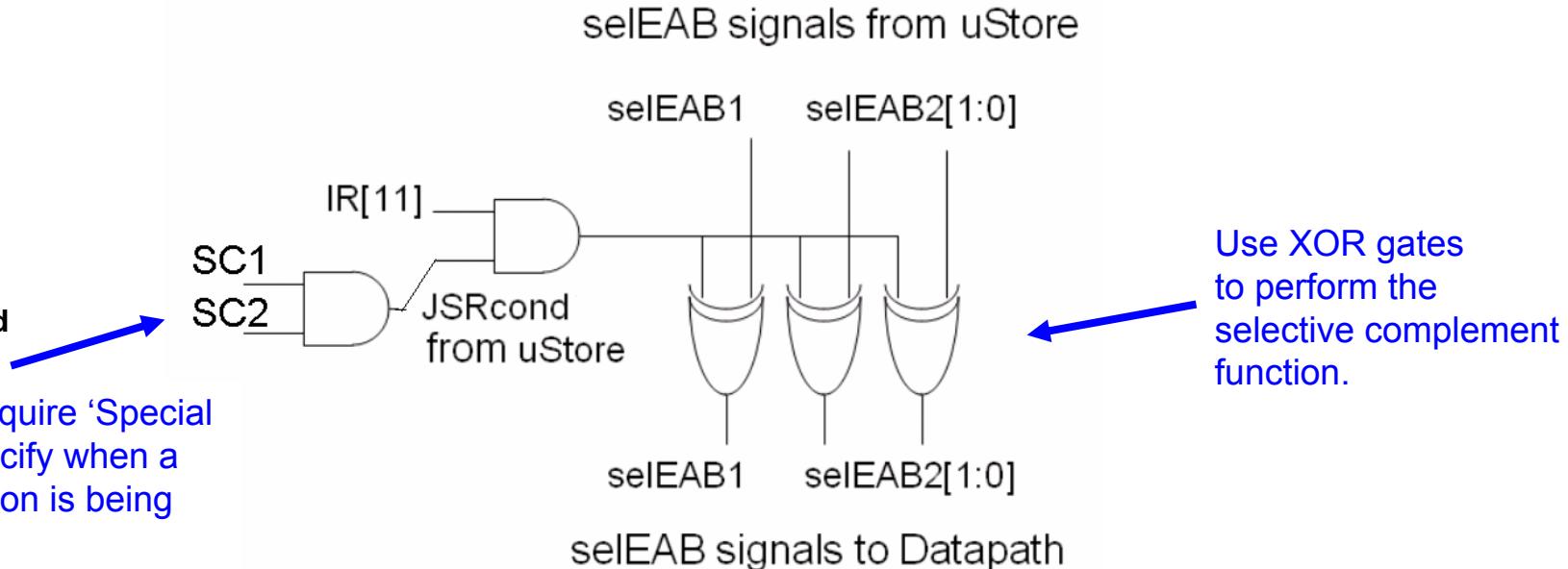
Selecting Jump Subroutine MUX control sources

Luckily, the control signals which differ are the complements of each other.



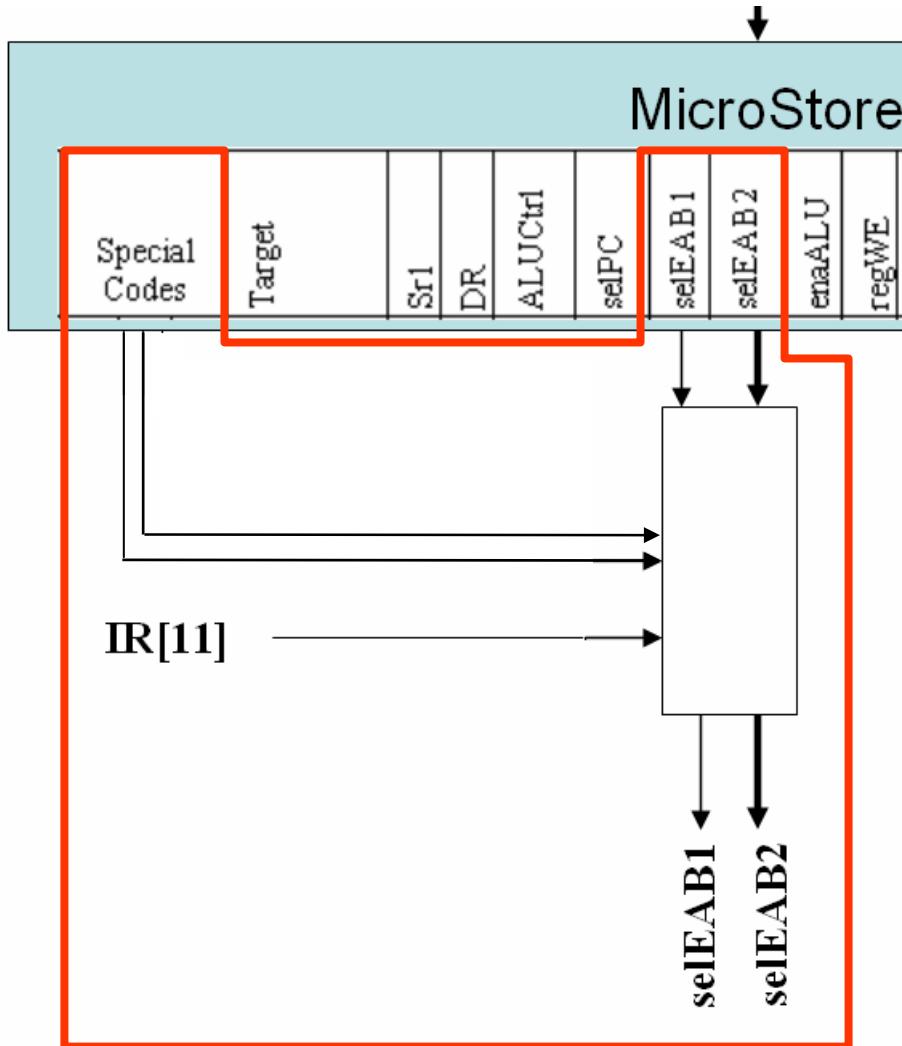
JSR	clock2	$PC \leftarrow EAddr$	$selEAB1 \leftarrow 0$
JSRR	clock2	$PC \leftarrow EAddr$	$selEAB1 \leftarrow 1$

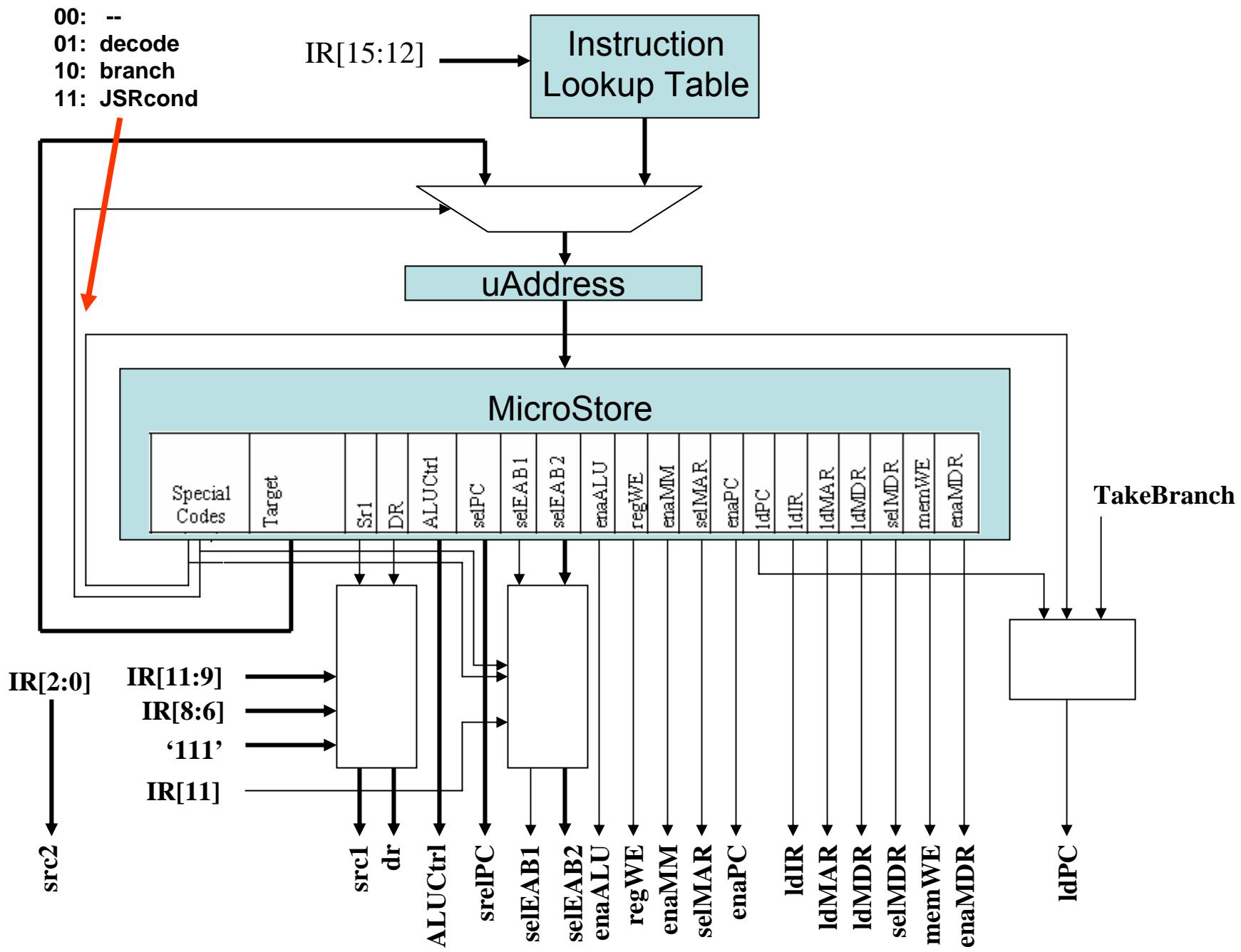
00: --
01: decode
10: branch
11: JSRcond



Again, we require 'Special Code' to specify when a JSR instruction is being executed.

Selecting Jump Subroutine MUX control sources





MicroStore

		Special Codes	Target Address	Sr1	DR	ALUctrl	selPC	selEAB1	selEAB2	enaALU	regWE	enaMM	selMAR	enaPC	1dPC	1dIR	1dMAR	1dMDR	selMDR	memWE	enaMDR
0	Reset	0 0	00001	0	0	00	00	0	00	0	0	0	0	0	0	0	0	0	0	0	0
1	Fetch	0 0	00002	0	0	00	00	0	00	0	0	0	0	1	0	0	1	0	0	0	0
2		0 0	00003	0	0	00	00	0	00	0	0	0	0	0	0	0	0	0	1	1	0
3		0 0	00004	0	0	00	00	0	00	0	0	0	0	0	1	0	0	0	0	0	1
4	Decode	1 0	00000	0	0	00	00	0	00	0	0	0	0	0	0	0	0	0	0	0	0
5	ADD	0 0	00001	0 0 01	00	0 00	1 1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
6	AND	0 0	00001	0 0 10	00	0 00	1 1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
7	BR	0 1	00001	0 0 00	01 0 10	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
8	JMP	0 0	00001	0 0 00	01 1 00	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0
9	JSR/R	0 0	01010	0 1 00	00	0 00	0	1	0	0	0	1	0	0	1	0	0	0	0	0	0
10		1 1	00001	0 0 00	01 1 00	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0
11	LD	0 0	01100	0 0 00	00	0 10	0	0	1 0	0	0	0	1	0	0	0	1	0	0	0	0
12		0 0	01101	0 0 00	00	0 00	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0
13		0 0	00001	0 0 00	00	0 00	0	1	0	0	0	0	0	0	0	0	0	0	0	0	1
14	LDI	0 0	01111	0 0 00	00	0 10	0	0	1 0	0	0	1	0	0	0	1	0	0	0	0	0
15		0 0	10000	0 0 00	00	0 00	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0
16		0 0	01100	0 0 00	00	0 00	0	0	0	0	0	0	0	0	0	0	1	0	0	0	1
17	LDR	0 0	01100	0 0 00	00	1 01	0	0	1 0	0	0	1	0	0	0	1	0	0	0	0	0
18	LEA	0 0	00001	0 0 00	00	0 10	0	1 1 0	0	0	1	1	0	0	0	0	0	0	0	0	0
19	NOT	0 0	00001	0 0 11	00	0 00	1 1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
20	ST	0 0	10101	0 0 00	00	0 10	0	0	1 0	0	0	1	0	0	0	0	1	0	0	0	0
21		0 0	10110	1 0 00	00	0 00	1	0	0	0	0	0	0	0	0	0	0	1	0	0	0
22		0 0	00001	0 0 00	00	0 00	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1
23	STI	0 0	11000	0 0 00	00	0 10	0	0	1 0	0	0	1	0	0	0	0	1	0	0	0	0
24		0 0	11001	0 0 00	00	0 00	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0
25		0 0	10101	0 0 00	00	0 00	0	0	0	0	0	0	0	0	0	0	1	0	0	0	1
26	STR	0 0	10101	0 0 00	00	1 01	0	0	1 0	0	0	1	0	0	0	0	1	0	0	0	0

Instruction Lookup Table

Op-code	Instruction	Next Address (decimal)	Next Address (binary)
0000	BR	7	00111
0001	ADD	5	00101
0010	LD	11	01011
0011	ST	20	10100
0100	JSR	9	01001
0101	AND	6	00110
0110	LDR	17	10001
0111	STR	26	11010
1000	RTI	----	---
1001	NOT	19	10011
1010	LDI	14	01110
1011	STI	23	10111
1100	JMP	8	01000
1101	----	----	----
1110	LEA	18	10010
1111	TRAP	----	----